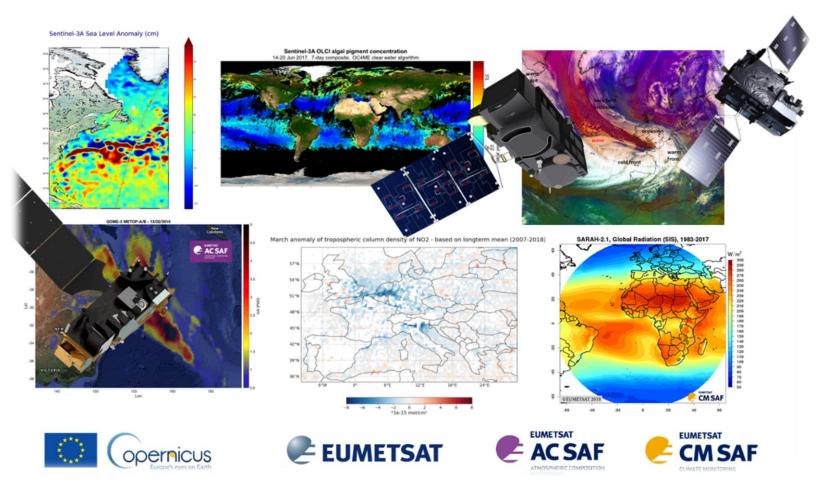
#### **Welcome to the 12<sup>th</sup> short online course in the series** The session will begin at 12 UTC



If you have technical issues, please send a message in the chat box to **Support**. For **Q&A**: go to Slido.com – event code: **#EUMSC12** 

#### **Upcoming Short Courses**

- 24 March 2021, 12:00 UTC How to build a case study - a demo session FOLLOW-UP with Ivan Smiljanic and Natasa Strelec Mahovic
- 14 April 2021, 12:00 UTC The Temperature of the Sea, with Lauren Biermann and Christine Träger-Chatterjee
- 12 May 2021, 12:00 UTC Spot atmospheric convection from satellite, with Natasa Strelec Mahovic and Ivan Smiljanic
- More to come ...

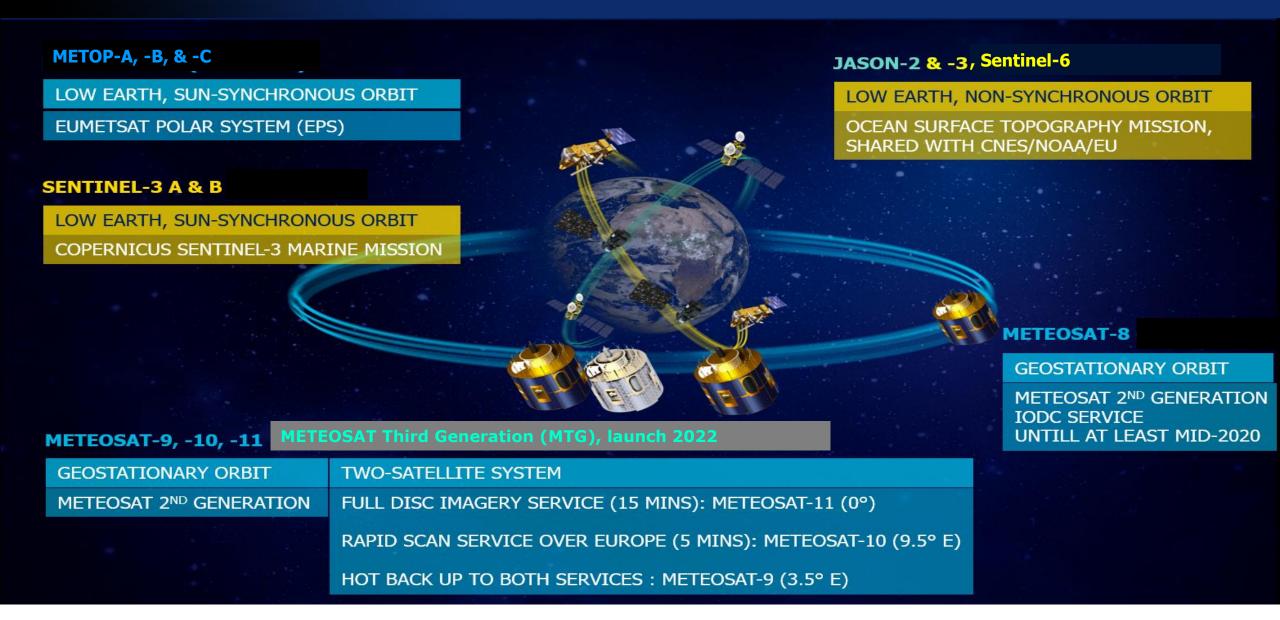
https://training.eumetsat.int/

→ Events → Short Courses

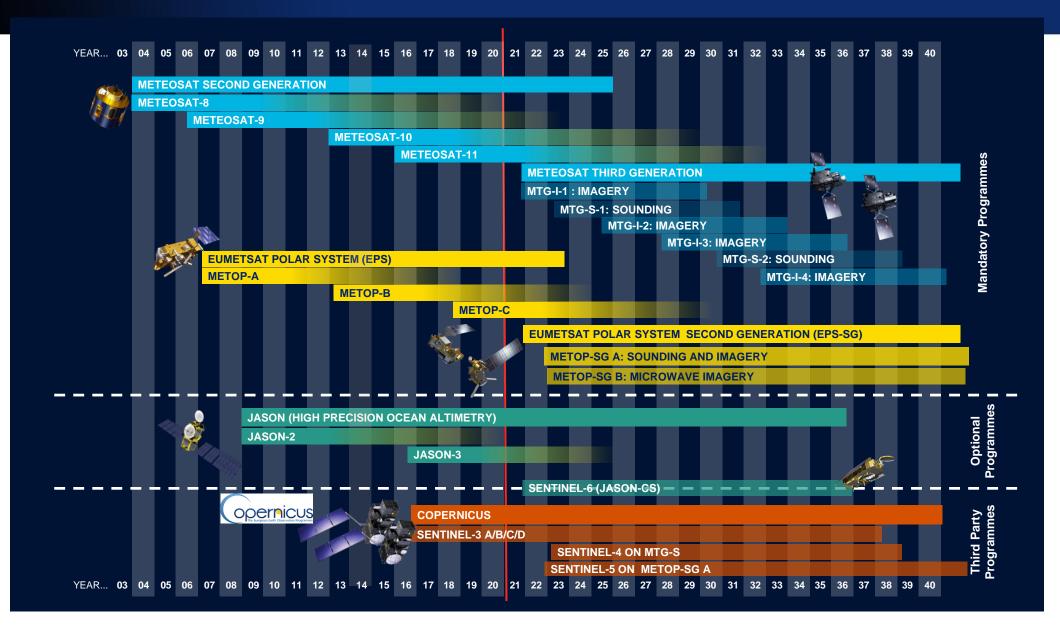




#### **Current EUMETSAT Satellites**



#### **EUMETSAT** committed to more & better observations until 2040



#### **Course Program**

12:00 UTC Welcome and Introduction

12:05 UTC How to build a case study

12:45 UTC Q&A and Wrap Up

Wed, 24 March, 12:00 UTC Follow-up session

**Discussion Q&A on:** slido.com #EUMSC12

Course Material: <a href="https://training.eumetsat.int/course/view.php?id=397">https://training.eumetsat.int/course/view.php?id=397</a>

If you have technical issues, please send a message in the chat box to **Support**. For **Q&A**: go to Slido.com – event code: **#EUMSC12** 





#### **EUMETSAT Short Courses:** How to build a case study?

17 March 2021

Natasa Strelec Mahovic and Ivan Smiljanic, **EUMETSAT** 





#### **Important questions**

- What is a case study (CS)?
- What is it good for?
- Who does CSs?

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• . . .

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How to do it?



< Anything
from a Twitter
post to a
scientific
paper >

4th European Conference on Severe Storms 10 - 14 September 2007 - Trieste - ITAL

#### APPLICATION OF CHANNEL DIFFERENCE 0.6 µm - 1.6 µm and 3.9 µm Channel in Automatic Convective Cells Detection

Nataša Strelec Mahović<sup>1</sup>, Barbara Zeiner<sup>2</sup>

| Meteorological and Hydrological Service, Grié 3, 10 000 Zagreb, Croatia, strelec@mail.dhz.hr <sup>2</sup> Central Institute for Meteorology and Geodynamics, Hohe Warte 38, 1190 Vienna, Austria, Barbara Zeiner@zamg ac.at (Dated: April 26, 2007)

#### I. INTRODUCTION

Automatic convective cloud detection methods, used operationally in many weather services, are often based undy on infin-red satellite data. However, such methods heave proven to be unsuccessful in many cases. Misdesto, large frontion occurs mostly due to detecting cirrus shields, large frontion occurs mostly due to detecting cirrus shields, large frontia masses or parts of fronts as convective clouds. If doubt-up temperature thresholds are set to lower values than low awater clouds and sometimes even for patches are detected ac convective clouds. This can cause many problems in operational forecessing process.

operational forecasting process.

Due to the properties of visible channels and that of 3.9 µm channel, enabling the differentiation of cloud phase and particle size and giving insight into the optical depth of clouds, an attempt has been made to reinforce the automatic convection detection method by introducing data from Meteosat SEVIRI channels 0.6, 1.6, and 3.9 µm.

#### II. DIFFERENCE OF VISIBLE CHANNELS 0.6

AND 1.6 µM.

The usage of visible channels in defining cloud phase and cloud particle size has been well documented and the properties of these channels are often exploited in composite images (Rosenfeld et al., 2004, MSGI Interpretation Guide). Reflectivity in visible channel of poin is the measure of the optical depth or albedo, therefore the highest reflectivity in visible channel of point in the processor of the properties of the optical depth or albedo, therefore the highest reflectivity in OS µm channel comes from optically thick water clouds and

snow. Reflectivity of very thick clouds can sometimes even be close to 100 %. On the other hand, transparent clouds (such as cirrus clouds) have much lower reflectivity. In FIG. 1 reflectivity in 0.6 µm channel is shown.

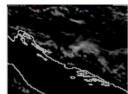


FIG. 1: Meteosat 8 SEVIRI 0.6 μm channel image from 0 2006, 10:57 UTC. Reflectivity from 50 to 100% is shown.

In the case selected here, convection started over the Dinaric Alps, but the cells cannot be identified in the  $0.6 \mu m$ 

Apart from enabling distinction between thick and thin clouds reflectivity in 1.6 µm channel (FIG. 2) enables distinction between ice and water clouds, since water clouds have much higher reflectivity in 1.6 µm channel than ice clouds. However, if reflectivity values, shown in FIG. 2 are analyzed, convective cells cannot be found easily.

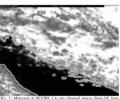


FIG. 2: Meteosat 8 SEVIRI 1.6 μm channel image from 0

In other words by looking at FIGs 1, and 2, it can be clearly seen that automatic detection of convective clouds would not be possible by using only 0.6 or only 1.6 jut channel data, even if the reflectivity threshold is set to values that can be expected in convective clouds. If 1.6 jut clouds the convective clouds, are also characteristic for other cloud features like transparent clouds, dissipating clouds etc. There can be no threshold set that would clearly point out only

convective cells.

In order to utilize properties of both channels at the same time, difference of reflectivity in 0.6 and 1.6 µm channels is used. The properties of this difference are often used in composite images. High value of the difference means that reflectivity in 0.6 µm channel is very high, meaning the clouds are dense and thick, whereas the reflectivity in 1.6 µm channel is very both, meaning the clouds are dense and thick, whereas the reflectivity in 1.6 µm channel is very loop because of the ice particles on top of the clouds. Therefore, very high values of difference are found only at convective to and only at convective top.

on the other hand, the areas which have low reflectivity in 1.6 μm channel due to small vertical depth have also low values in 0.6 μm channel, and can therefore by

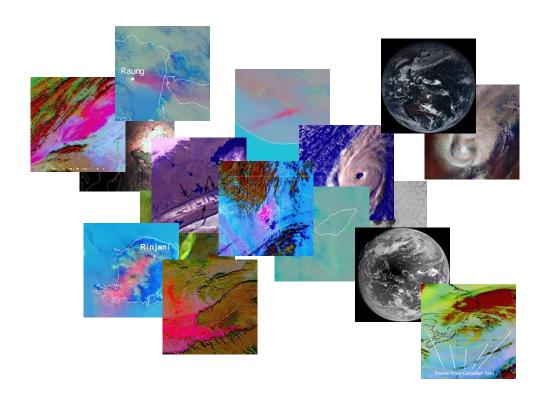


- "A case study involves an up-close, in-depth, and detailed examination of a particular case or cases, within a real-world context." – Wikipedia
- Or a case-based story telling (scientific research) about different:
  - Conceptual models in Earth-Atmosphere system
  - Satellite system capabilities
  - Data and product utility
  - Particular weather event of high impact/interest
  - Climate (change) description

•



EUMETSATCase StudyLibrary

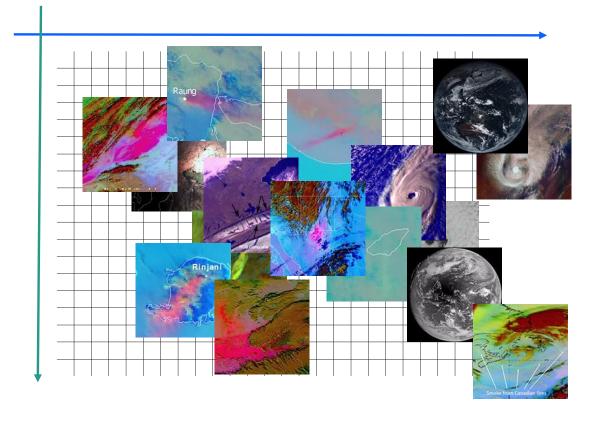


 EUMETSAT Case Study Library

Cloud Optical Thick Cloud Phase RGB Day Microphysics Cloud Top Height Convection RGB **Atmospheric** and Surface **Dust RGB** /ectors

**FEATURE** 

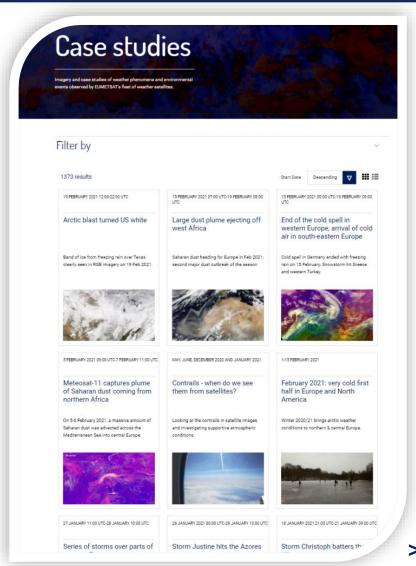
**Aerosol Airmass Boundary Algae Blooms Asteroid Atmospheric Pollution Atmospheric River Aurora borealis Bora Burned Area Cirrus Climate Monitoring** Cloud deck **Convergence Line** Cumulus Cyclogenesis **Extratropical** transition Fire **Foehn** 



Precipitation Estimate



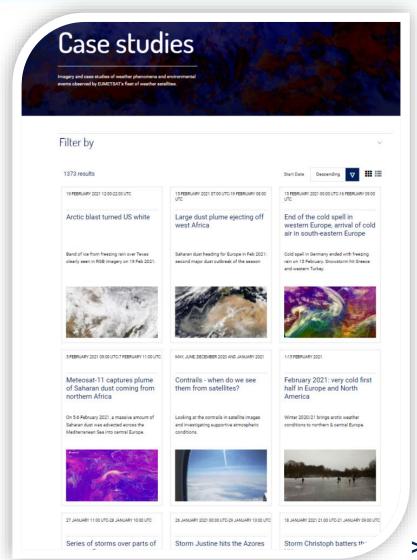
 EUMETSAT Case Study Library



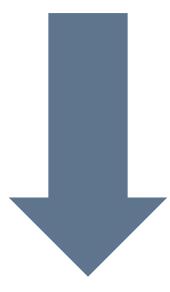
> https://www.eumetsat.int/case-studies



EUMETSAT Case Study Library



**Check** examples here



> https://www.eumetsat.int/case-studies

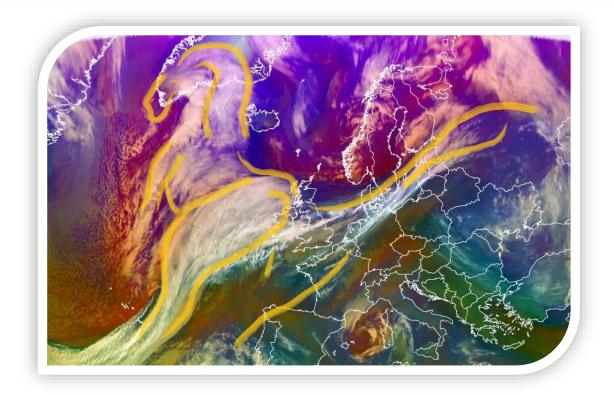


# What is a CS good for?



## What is a case study good for

- Multiple (hidden) reasons:
  - handling data
  - defining/tuning tools
  - revealing physics
  - defining advantages and constrains
  - comparing instruments
  - redefining needs
  - develop 'feeling' for data
  - expand knowledge
  - inventing
  - networking
  - user training
  - •
  - have fun



## Who does the CSs?



## Who does the CSs

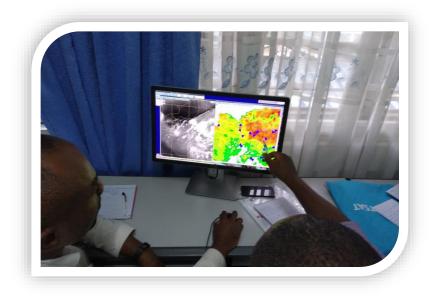




#### How do we make the CSs?

#### How do we make the CSs

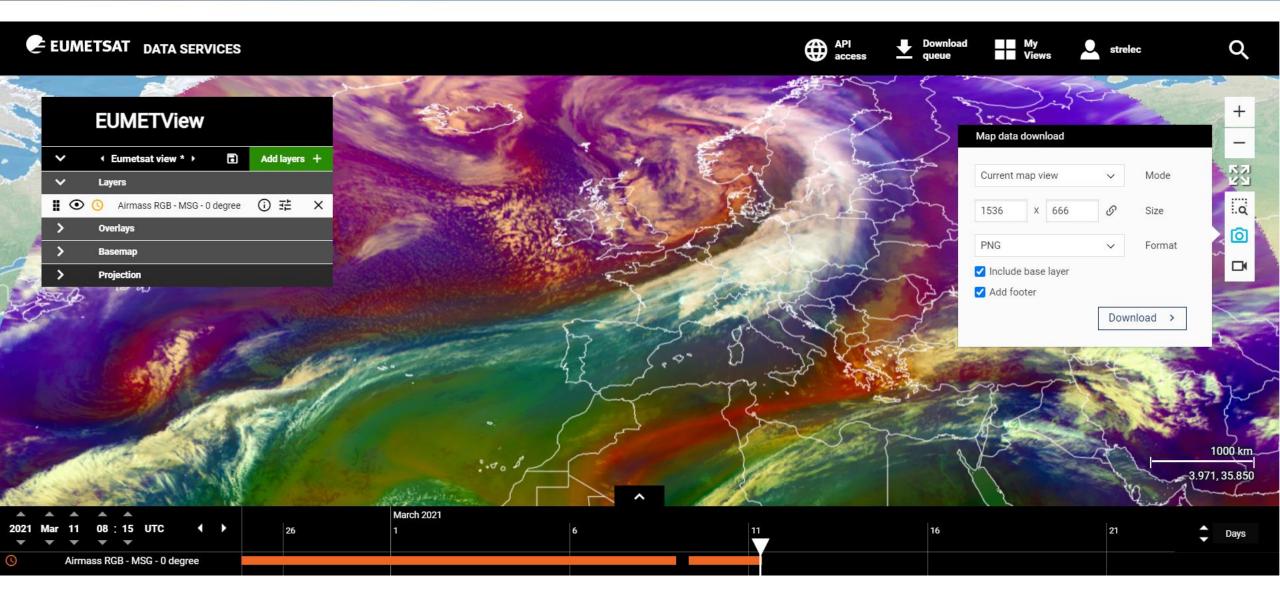
- 1. Idea
- 2. Data exploration
- 3. Expert collaboration
- 4. Revision
- 5. Web publication



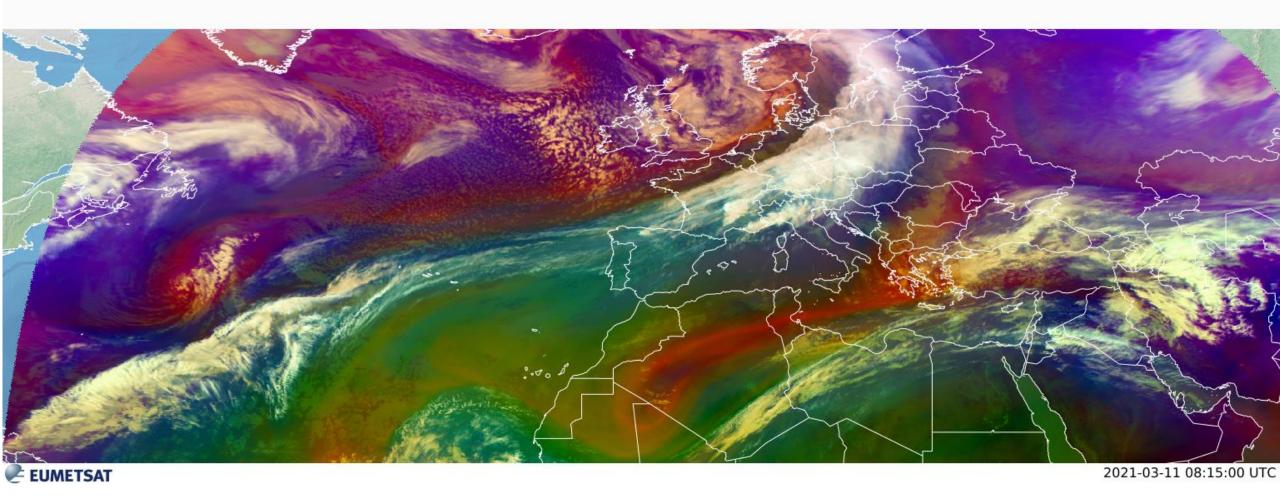
#### How do we make the CSs – data, tools, resources

- Where do we get data and how?
- Which tools we can use for visualisation?
- Training resources: Satmanu, Quick Guides, Cheatsheets, Colour interpretation guides
- Which expert group to consult?
- Info sources: WMO Saturn and Oscar ...

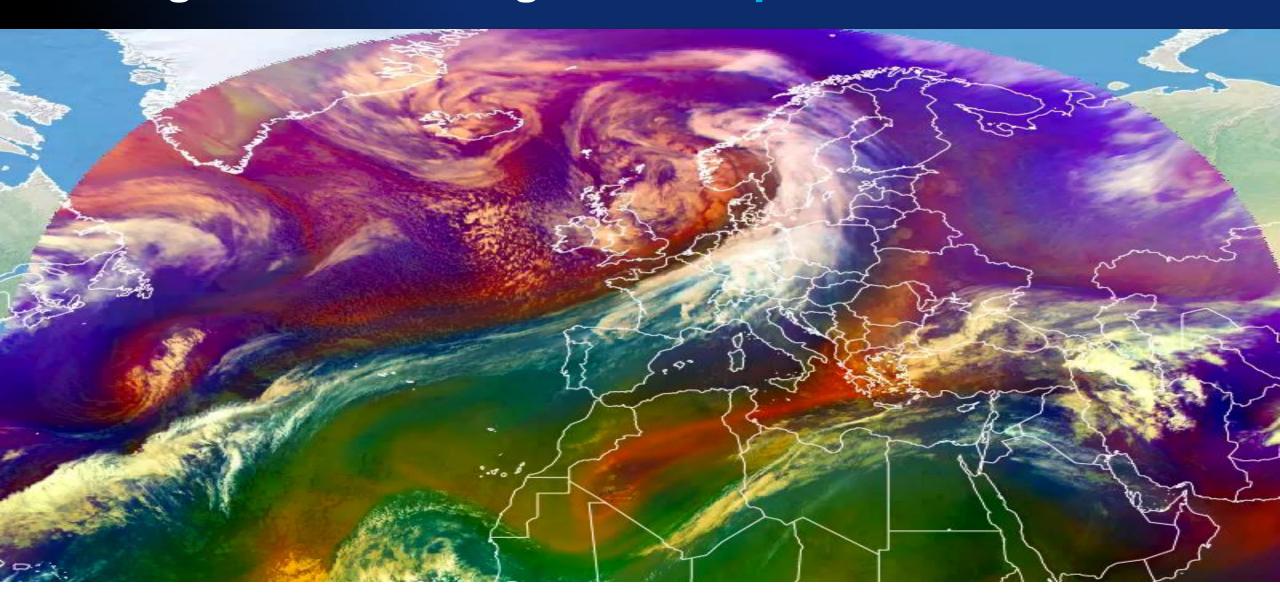
#### https://view.eumetsat.int



# https://view.eumetsat.int



# https://view.eumetsat.int



#### https://view.eumetsat.int

#### Current data collections

**METOP** 





SST PRODUCTS

MFG/MSG



ISG SEVIRI RADIOMETRY PRODUCTS

MSG CLOUD MASK PRODUCTS



PRECIP. PRODUCTS

SENTINEL-3A / 3B

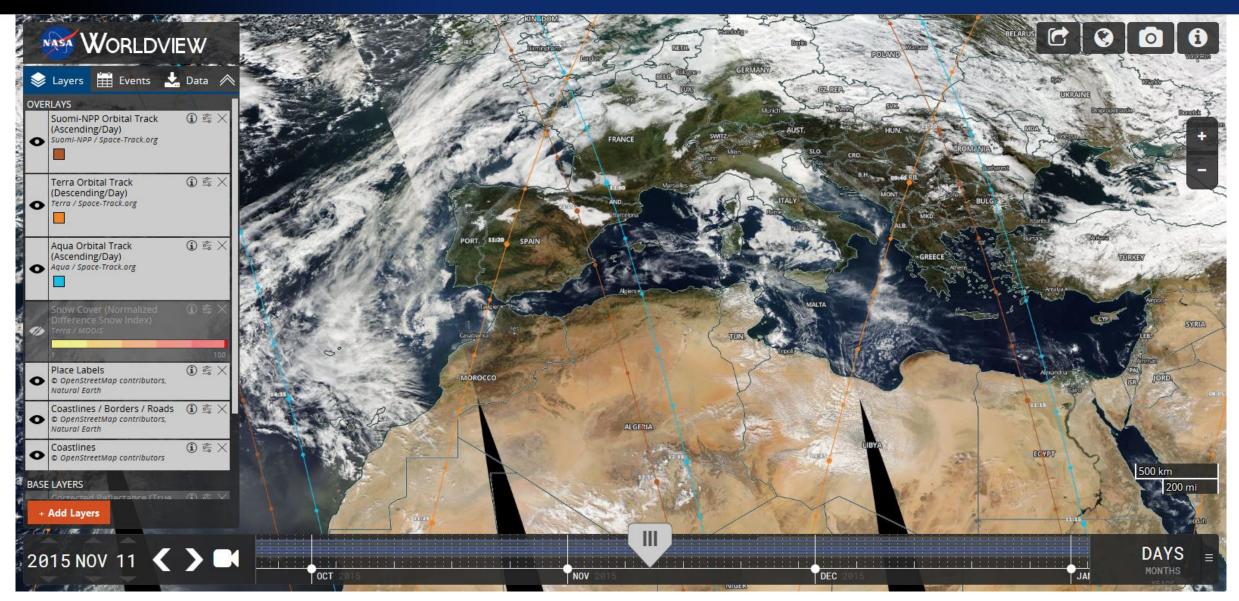
SLSTR RADIOMETRY PRODUCTS
OLCI RADIOMETRY PRODUCTS



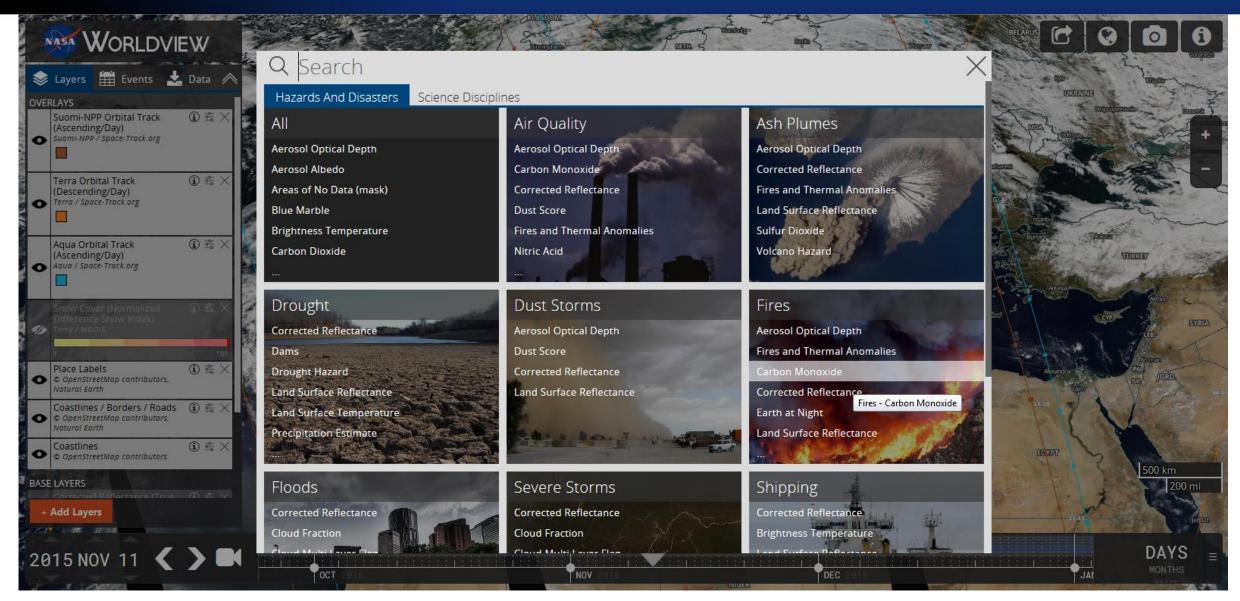
| Product   | Platform        | OGC Service |
|---|-----------------|-------------|
| Metop AVHRR RGB Clouds (accumulated orbits)                       | Metop A, B, C   | WMS         |
| Metop AVHRR Natural Colour + Fog (accumulated orbits)             | ,               | WMS         |
|   | Metop A, B, C   |             |
| Metop AVHRR IR 10.8   | Metop A, B, C   | WMS         |
| Global AVHRR SST  | Metop B         | WMS, WCS    |
| ASCAT L2 Coastal Winds at 12.5 km                                 | Metop A, B, C   | WMS, WFS    |
|   |                 |             |
| Meteosat single channel imagery (10.8, 3.9, 0.6, 6.2), RGB Day    |                 |             |
| Microphysics; Ash; Dust; E-View, Fog, Convection, Natural Colour, | 0 deg., IODC    | WMS         |
| Snow, Nat. Colour Enhanced, Airmass, Tropical Airmass.            |                 |             |
| Meteosat single channel imagery (3.9), RGB Day Microphysics;      | RSS             | WMS         |
| Natural Colour, Nat. Colour Enhanced, Airmass, Tropical Airmass.  | 1133            | WW          |
| Visualised products; CTH, CLM, Active Fire                        | 0 deg., IODC    | WMS         |
| Precipitation (MPE)   | IODC            | WMS         |
| Precipitation (H03B)  | 0 deg.          | WMS         |
|   |                 |             |
| Sentinel 3 OLCI L1 RGB orbits                                     | Sentinel 3A & B | WMS         |
| Sentinel 3 OLCL L2 CHL Concentration orbits                       | Sentinel 3A & B | WMS, WCS    |
| Sentinel 3 SLSTR L2 SST orbits                                    | Sentinel 3A & B | WMS, WCS    |
| Sentinel 3 OLCI L1 RGB accumulated orbits over a day orbits       | Sentinel 3A + B | WMS         |
| Sentinel 3 OLCL L2 CHL Concentration accumulated orbits / day     | Sentinel 3A + B | WMS, WCS    |
| Sentinel 3 SLSTR L2 SST accumulated orbits / day                  | Sentinel 3A + B | WMS, WCS    |



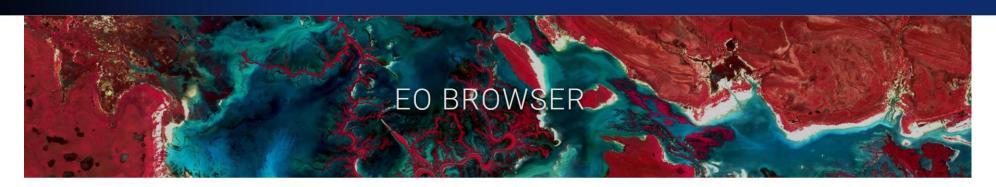
#### https://worldview.earthdata.nasa.gov



## https://worldview.earthdata.nasa.gov

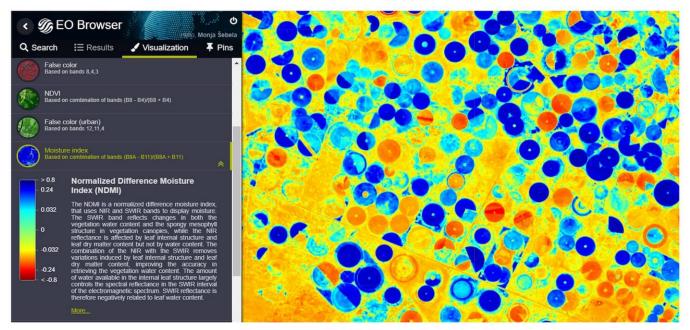


#### https://www.sentinel-hub.com/explore/eobrowser/



#### Custom Visualization

Satelite imagery in EO Browser can be visualized based on user's desired configuration. There are already several visualizations with legends and descriptions prepared for you, such as true color, false color, NDVI, EVI, etc.



## http://rammb-slider.cira.colostate.edu/



#### **New EUMETSAT Data Services**

Data Store
Data Tailor

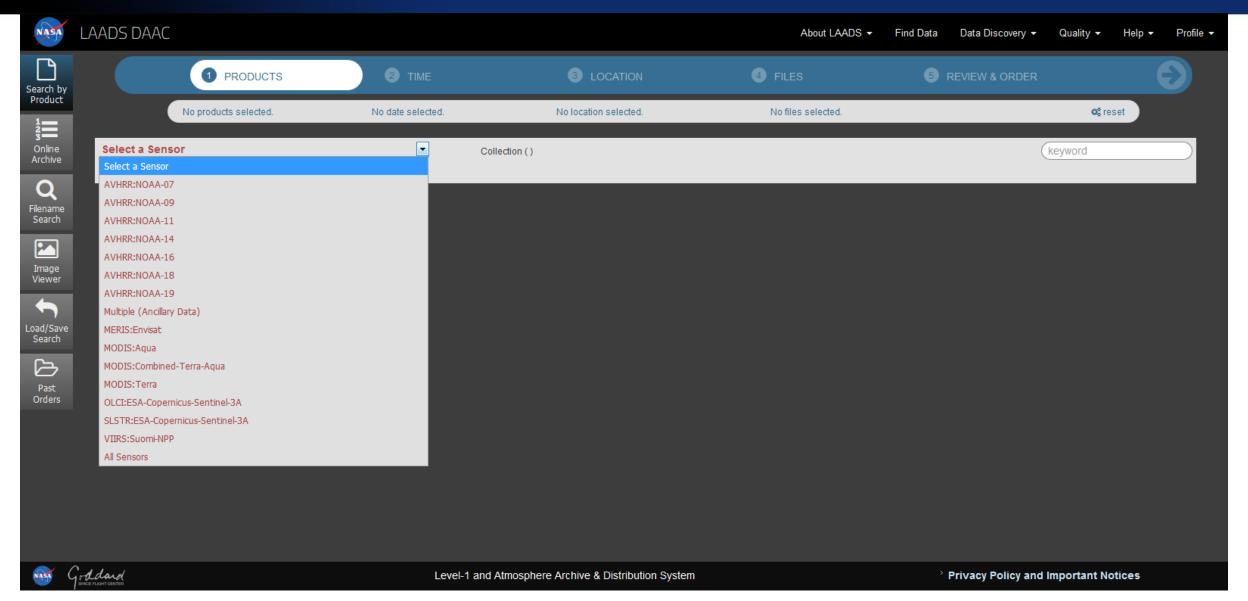
http://eumetrain.org/data/6/603/snow\_ew\_2021\_s2c.pdf

Knowledge base for services

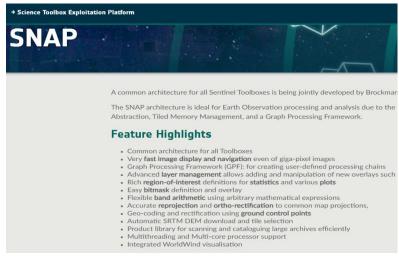
<u>EUMETSAT User Support - EUMETSAT Public Confluence</u> (atlassian.net)



# https://ladsweb.modaps.eosdis.nasa.gov/search/



#### Visualization Software



https://step.esa.int/main/toolboxes/snap/

# Panoply netCDF, HDF and GRIB Data Viewer panoply \PAN-uh-plee\, noun: 1. A splendid or impressive array... Perturbation Potential Temperature Perturbation Potential Temperature | Perturbation

The current version of Panoply is 4.12.4, released 2021-02-28

Panoply is a cross-platform application that runs on Macintosh, Windows, Linux and other desktop computers

https://www.giss.nasa.gov/tools/panoply/



The Satellite Information Familiarization Tool, or SIFT, is a meteorological satellite imagery visualization software application with a graphical user interface designed at the University of Wisconsin Space Science and Engineering Certer (SSEC) to run on mid-range consumer grade computers and notebooks. Built on Python, SIFT runs on Windows, Mac, and some Linux operating systems. The National Weather Service (NWS) originally funded the development of SIFT for use as a training application for Himawari-8 imagery at the forecast office in Guam, but SIFT has evolved into the primary learning software that accompanies the training exercises on the new-generation geostationary weather satellities.

SIFT is free to download and use as-is, with no expressed warranty or guarantee of support. Technical specifications for SIFT are <u>available</u>. Workstations with a solid-state drive (SSD) will provide the best user experience.

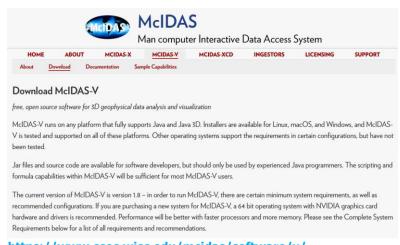
Users can obtain Geostationary Operational Environmental Satellitie R-Series (GOES-R) Advanced Baseline Imager (ABI) data readable with SIFT for download from the NOAA Comprehensive Large Array-data Stewardship System (CLASS), or, alternatively, the Google Cloud Platform Marketolace. First-time users may wish to watch a video describing the basis SIFT functionalities.

The latest version of SIFT is 1.1.6, released on 11 January 2021. Our <u>FTP site</u> hosts SIFT installers for the two primary operating systems. Previous versions of SIFT can also be downloaded there.

- · Windows version (841 MB)
- Mac version (546 MB)
- Linux version (723 MB)

For specific installation instructions, see  $\underline{\text{GitHub}}$ . Open source code is available to download from  $\underline{\text{GitHub}}$  as well.

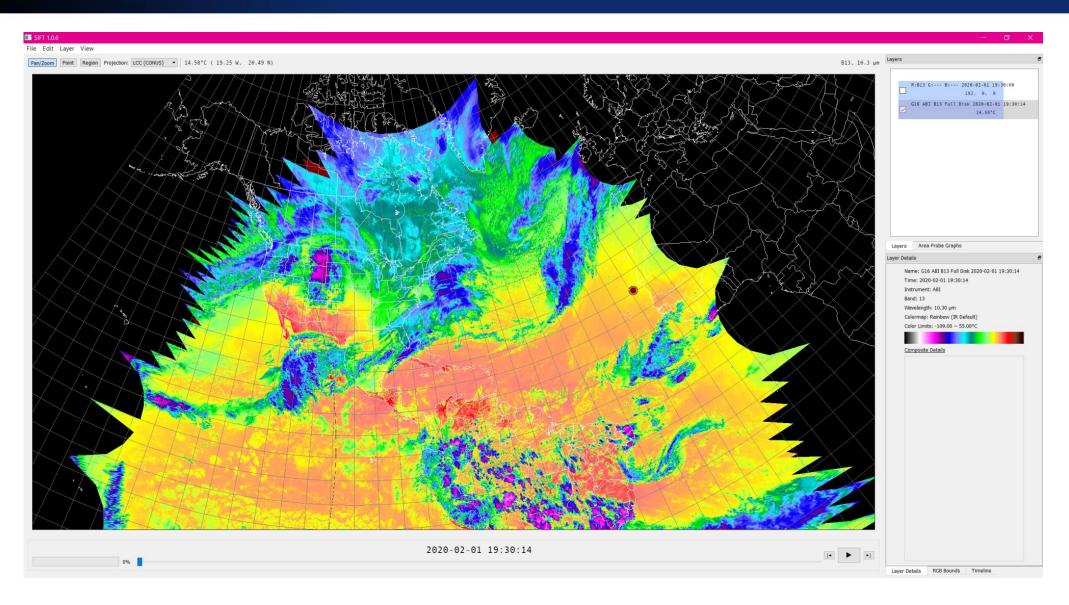
#### http://sift.ssec.wisc.edu/



https://www.ssec.wisc.edu/mcidas/software/v/



# Visualization Software - Example



#### Images + NWP model data

#### http://eumetrain.org/e-port



#### Concept of ePort

ePort is a product of EUMeTrain which has been developed to allow you to combine a range of EUMETSAT satellite images with satellite derived products and numerical model fields.

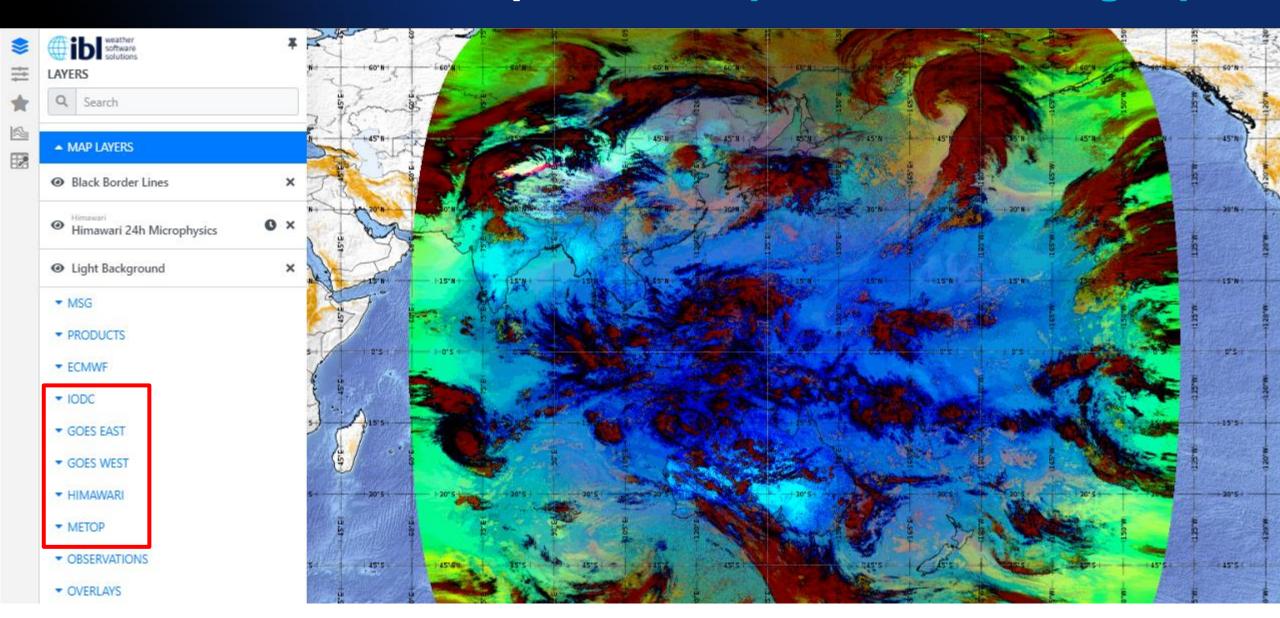
ePort has switched to a web map service in 2015, the old ePort will is not available anymore.

All images generated are automatically stored in an archive which makes it possible for you to do a qualitative research.



## Satellite data in the E-port

## http://eumetrain.org/e-port



## Assistance tools: Next generation GEO - cheat sheet

Er an C in it

| "Colloquial"<br>channel name | Applications              |
|------------------------------|---------------------------|
| Blue                         | aerosol, surface features |
| Green                        | aerosol, vegetation       |
| Red                          | fog, insolation, winds    |
| Veggie                       | vegetation, winds         |
| Low-level WV                 | water vapour, winds       |
| Cirrus                       | thin cirrus               |
| Snow/Ice                     | cloud phase, snow/ice     |
| Particle Size                | particle size, vegetation |
| Fire                         | microphysics, fires       |
| High-level WV                | WV, winds, rainfall       |
| Mid-level WV                 | WV, winds, rainfall       |
| Lower-level WV               | WV, winds, SO2            |
| Cloud-top phase              | cloud phase, SO2          |
| Ozone                        | total O3, turbulence      |
| Clean IR                     | SST, clouds temp          |
| IR Longwave                  | SST, clouds temp, rainfal |
| Dirty IR                     | TPW, dust, ash            |
| CO2                          | air temp, cloud height    |

| Ch.<br>No. | Central<br>λ (μm) | λ width<br>(μm) | Resolution<br>(km) |
|------------|-------------------|-----------------|--------------------|
| 1          | 0.47              | 0.04            | 1.0                |
|            |                   |                 |                    |
| 2          | 0.64              | 0.10            | 0.5                |
| 3          | 0.86              | 0.04            | 1.0                |
|            |                   |                 |                    |
| 4          | 1.38              | 0.02            | 2.0                |
| 5          | 1.61              | 0.06            | 1.0                |
| 6          | 2.25              | 0.05            | 2.0                |
| 7          | 3.90              | 0.20            | 2.0                |
| 8          | 6.19              | 0.80            | 2.0                |
| 9          | 6.95              | 0.40            | 2.0                |
| 10         | 7.34              | 0.20            | 2.0                |
| 11         | 8.50              | 0.40            | 2.0                |
| 12         | 9.61              | 0.40            | 2.0                |
| 13         | 10.35             | 0.50            | 2.0                |
| 14         | 11.20             | 0.80            | 2.0                |
| 15         | 12.30             | 1.00            | 2.0                |
| 16         | 13.30             | 0.60            | 2.0                |

Advanced Baseline Imager

| Flexible Combined Imager |                   |                 |                    |  |  |
|--------------------------|-------------------|-----------------|--------------------|--|--|
| Ch.<br>No.               | Central<br>λ (μm) | λ width<br>(μm) | Resolution<br>(km) |  |  |
| 1                        | 0.44              | 0.06            | 1.0                |  |  |
| 2                        | 0.51              | 0.04            | 1.0                |  |  |
| 3                        | 0.64              | 0.05            | 1.0 (*0.5)         |  |  |
| 4                        | 0.86              | 0.05            | 1.0                |  |  |
| 5                        | 0.91              | 0.02            | 1.0                |  |  |
| 6                        | 1.38              | 0.03            | 1.0                |  |  |
| 7                        | 1.61              | 0.05            | 1.0                |  |  |
| 8                        | 2.25              | 0.05            | 1.0 (*0.5)         |  |  |
| 9                        | 3.80              | 0.40            | 2.0 (*1.0)         |  |  |
| 10                       | 6.30              | 1.00            | 2.0                |  |  |
|                          |                   |                 |                    |  |  |
| 11                       | 7.35              | 0.50            | 2.0                |  |  |
| 12                       | 8.70              | 0.40            | 2.0                |  |  |
| 13                       | 9.66              | 0.30            | 2.0                |  |  |
| 14                       | 10.50             | 0.70            | 2.0 (*1.0)         |  |  |
|                          |                   |                 |                    |  |  |
| 15                       | 12.30             | 0.50            | 2.0                |  |  |
| 16                       | 13.30             | 0.60            | 2.0                |  |  |

| Auv        | anceu             | IIIIIawaii      | Imager             |
|------------|-------------------|-----------------|--------------------|
| Ch.<br>No. | Central<br>λ (μm) | λ width<br>(μm) | Resolution<br>(km) |
| 1          | 0.47              | 0.05            | 1.0                |
| 2          | 0.51              | 0.02            | 1.0                |
| 3          | 0.64              | 0.03            | 0.5                |
| 4          | 0.86              | 0.02            | 1.0                |
|            |                   |                 |                    |
|            |                   |                 |                    |
| 5          | 1.61              | 0.02            | 2.0                |
| 6          | 2.25              | 0.02            | 2.0                |
| 7          | 3.88              | 0.22            | 2.0                |
| 8          | 6.24              | 0.37            | 2.0                |
| 9          | 6.94              | 0.12            | 2.0                |
| 10         | 7.34              | 0.17            | 2.0                |
| 11         | 8.59              | 0.32            | 2.0                |
|            |                   |                 |                    |

0.30

2.0

11.23 12.38

Advanced Himawari Imager

| SEVIRI   | Proxy instruments -<br>MODIS | λ(μm) / Res (<br>VIIRS | km)<br>SLSTR     |
|----------|------------------------------|------------------------|------------------|
| 200      | 0.44/1.0                     | 0.45/0.75              | -                |
| -        | 0.55/0.5                     | 0.55/0.75              | 0.55/0.5         |
| 0.64/3.0 | 0.65/0.25                    | 0.64/0.375             | 0.67/0.5         |
| 0.81/3.0 | 0.86/1.0                     | 0.87/0.375             | 0.86/0.5         |
| -        | 0.91/1.0                     | -                      |                  |
| -        | 1.38/1.0                     | 1.38/0.75              | 1.38/0.5         |
| 1.64/3.0 | 1.64/0.5                     | <b>1.61</b> /0.375     | <b>1.61</b> /0.5 |
| -        | ,                            | 2.25/0.75              | 2.25/0.5         |
| 3.92/3.0 | 3.75/1.0                     | 3.74/0.375             | 3.74/1.0         |
| 6.25/3.0 | · -                          | -                      | -                |
| A        | 6.72/1.0                     | -                      | -                |
| 7.35/3.0 | 7.33/1.0                     | -                      | -                |
| 8.70/3.0 | 8.55/1.0                     | 8.55/0.75              | -                |
| 9.66/3.0 | 9.73/1.0                     | -                      | -                |
| 10.8/3.0 | 11.0/1.0                     | <b>10.8</b> /0.75      | <b>10.8</b> /1.0 |
| -        | -                            | <b>11.5</b> /0.375     | -                |
| 12.0/3.0 | 12.0/1.0                     | 12.0/0.75              | 12.0/1.0         |
| 13.4/3.0 | 13.3/1.0                     | -                      | -                |



| Full disc   |  | Full disc                                     | ?                  | 10 min | 1.0 - 2.0 km | Full disc             | ?                 | 10 min  | 0.5 - 2.0 km |
|---|--|---|--------------------|--------|--------------|-----------------------|-------------------|---------|--------------|
| Continental<br>US (CONUS)                         |  | Rapid Scan                                    | LAC 4<br>(top disc | 2.5min | 0.5 - 1.0 km | Japan region          | 2000 x<br>1000 km | 2.5 min | 0.5 - 2.0 km |
| Mesoscale   |  |   | quarter)           |        |              | Target area           | 1000 x<br>1000 km | 2.5 min | 0.5 - 2.0 km |
| Flex Mode: The<br>minutes, a CO<br>every 60 secon |  | * The channels delivered in ad configuration. |                    |        |              | Landmark area<br>/ x2 | 1000 x<br>500 km  | 0.5 min | 0.5 - 2.0 km |

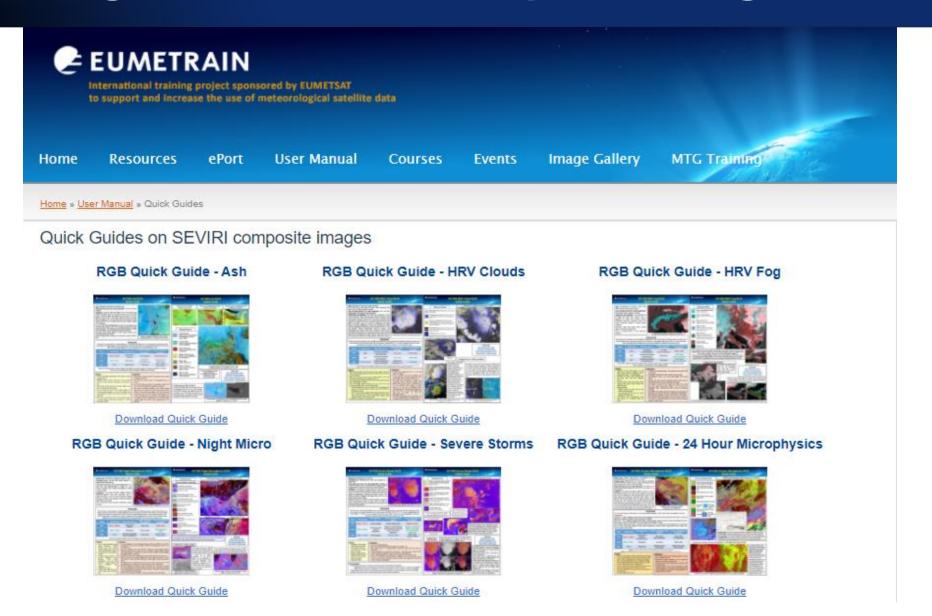
## Assistance tools: Next generation GEO - cheat sheet

|                       | Pioneer instrument - LIS  | Geostationary Lightning Mapper   | Lightning Imager   | Lightning Mapping Imager   | Ground network - GLD360  |
|-----------------------|---|--|--|--|--|
| Platform              | TRMM/ISS  | GOES-16  | MTG-I  | Feng-Yun-4   | ~  |
| Orbit                 | LEO   | GEO  | GEO  | GEO  | ~  |
| Description           | CCD camera operating at 777.4 nm (O2) to count flashes and measure their intensity  | CCD camera operating at 777.4 nm (O2) to count flashes and measure their intensity | CCD camera operating at 777.4 nm (O2), flash counts and intensity measurement. Detection efficiency > 90 % for events of 10 μ-m-2-sr-1 at 45° (day), 4 μ-m-2-sr-1 (night). FAR < 2 s-1 | CCD camera operating at 777.4 nm (O2) to count flashes and measure their intensity | A network of sensors operating in the Very Low<br>Frequency (VLF) band and measuring<br>horizontal magnetic fields of radio impulses<br>generated by return strokes and large cloud<br>pulses. |
| Scanning<br>technique | Pushbroom, matrix array of 128 x 128 detectors, swath 600 km; each earth location observed continuously (every 2 ms) for about 90 s                       | Electronic, 3-axis stabilised satellite, single detector matrix                    | Electronic, 3-axis stabilised satellite, single detector matrix  | Electronic, 3-axis stabilised satellite, single detector matrix                    | Fixed location, ground-Based detectors   |
| Resolution            | 4 km  | 8 km at s.s.p. (sub-satellite point)   | 10 km  | 7.8 km at s.s.p.   | 2-3 km   |
| Coverage<br>/Cycle    | Passes at ~ 100-min intervals with longer gaps once or twice per day. More regular coverage at 15°N and 15°S. On ISS: latitude coverage extended to 51.6° | Large fraction of the disk continuously observed (time resolution 2 ms)            | Full disk continuously observed (time resolution ~ 2 ms)   | Full disk continuously observed (time resolution ~ 2 ms)                           | Global   |

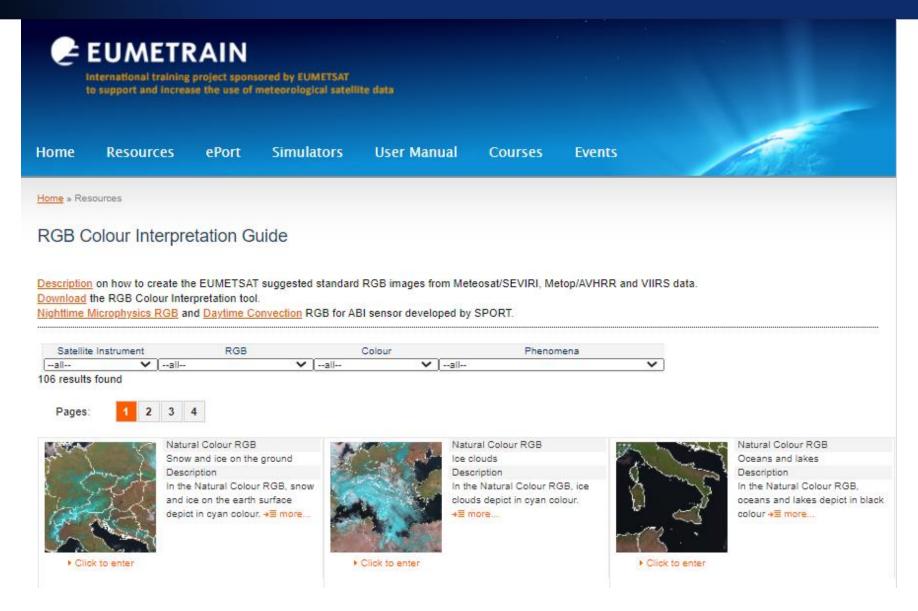
|                       | Proxy instrument - IASI   | Proxy instrument - CrIS   | Infra-Red Sounder  | Geostationary Interferometric IRS   |
|-----------------------|---|---|--|---|
| Platform              | EPS-A/B/C   | NOAA-20   | MTG-S  | Feng-Yun-4  |
| Orbit                 | LEO   | LEO   | GEO  | GEO   |
| Description           | Interferometer with 8461 channels, with one embedded IR imaging channel                           | Interferometer with three IR bands, 1305 channels in initial operation mode. Future operation mode will have 2211 channels with the same full spectral resolution in all three bands. | Interferometer with large detector arrays for simultaneous sounding of more pixels         | MWIR/TIR interferometer with large detector arrays for simultaneous sounding of more pixels. 913 channels on the first flight unit, 1188 on follow-on flight units. |
| Scanning<br>technique | Cross-track: 30 steps of 48 km ssp, swath<br>2130 km - Along-track: one 48-km line<br>every 8 s   | Cross-track: 32 steps of 48 km 5.5.p.,<br>swath 2200 km - Along-track: one 48-km  | Mechanical, bi-axial, 3-axis stabilised satellite, step-<br>and-dwell of a detector matrix | Mechanical, bi-axial, 3-axis stabilised satellite, step-<br>and-dwell of a detector matrix.   |
| Resolution            | 4 x 12-km IFOV close to the centre of a 48<br>x 48 km2 cell (average sampling distance:<br>24 km) | line every 8 s  3 x 3 14 km IFOV covering a 48 x 48 km2 cell (average sampling distance: 16 km)   | 4.0 km   | Prototype flight 16 km, follow-on 8 km, at <u>s.s.p.</u> .<br>Supporting VIS: 2 km at <u>s.s.p.</u>   |
| Coverage<br>/Cycle    | Near-global coverage twice/day  | Near-global coverage twice/day  | Full disk in 60 min. Limited areas in correspondingly shorter time intervals               |   |



## RGB Quick guides, colour interpretation guides

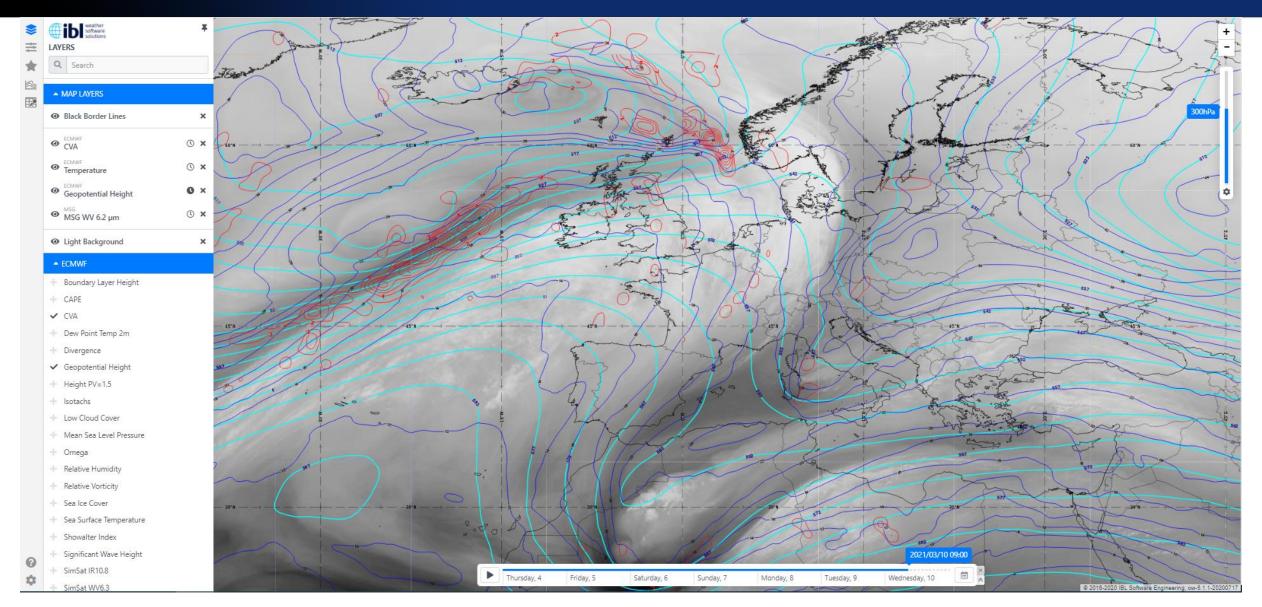


#### RGB Quick guides, colour interpretation guides

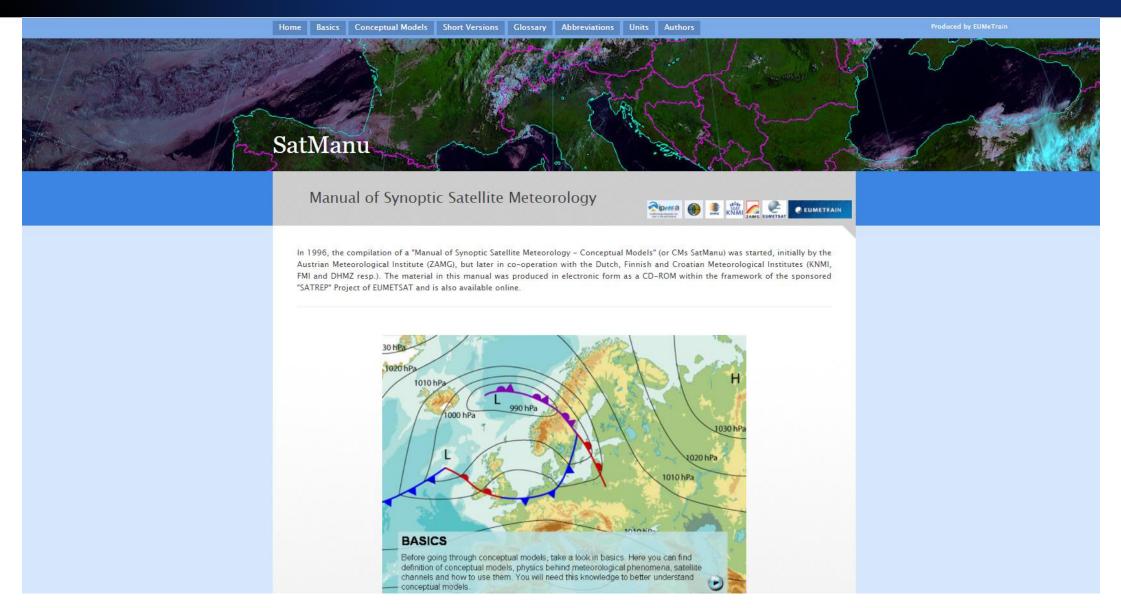


# Images + NWP model data

## http://eumetrain.org/e-port



#### Satmanu



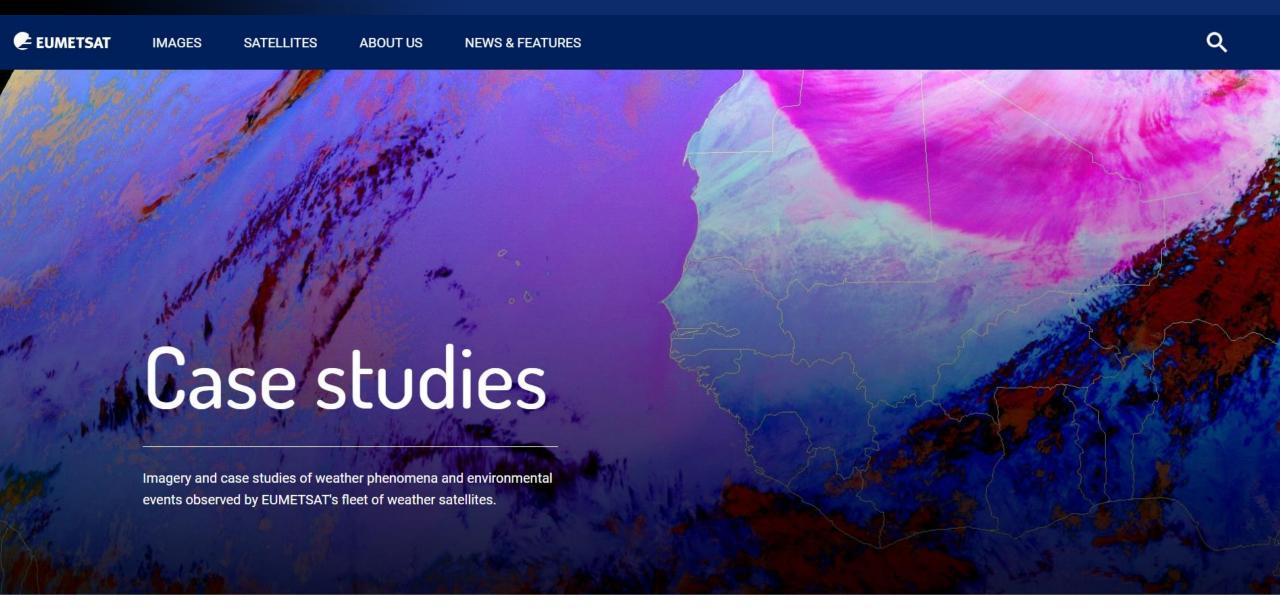
## Consult colleagues, expert groups

- regional training communities
- CWG
- MTG Forum
- EUMETSAT trainers/experts
- topcase email



#### Case study factory

## https://www.eumetsat.int/case-studies



Want to join us? Have ideas of your own?

# Let's do a CS together!



## Follow-up demo session

- In a week time (24<sup>th</sup> March) we get together and discuss:
  - Objective of your case study (Why did you choose it? What do you want to show? What is the importance of the CS?)
  - Scope of your CS (Which case? Which conceptual models to use? What kind of data?)
  - Which tools did/would you utilise?
  - Who did/would you collaborate with?
  - Would you like to publish the CS in the EUMETSAT case study library?



https://padlet.com/TrainingEUMETSAT/z8es6rqcwo7y7ecs



Enjoy making a case study!

See you next Wednesday!

