

Recent Developments in Altimetry Measurements – Sentinel–6 Michael Freilich Vinca Rosmorduc, CLS (with material from a number of agencies and altimetry users)

Short Course - 2022/09/29

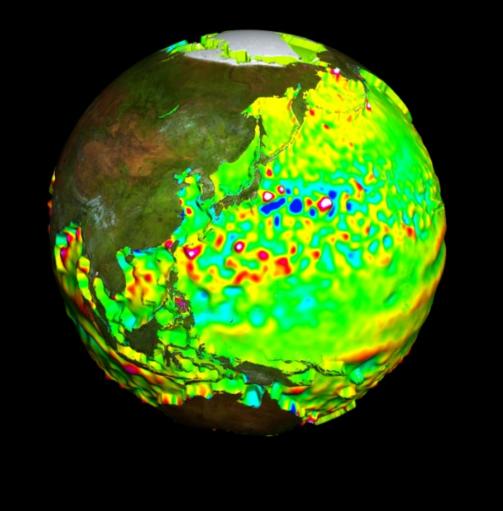
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Radar altimetry data uses

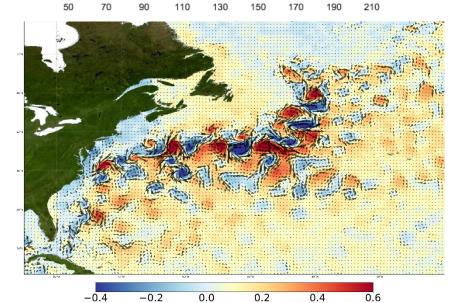
What can sea heights show? Eddies, gyres and meanders – variability in the ocean

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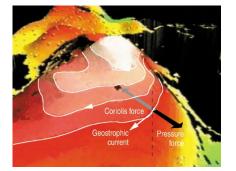
Eddies (turbulence) in a major current (Kuroshio)



<figure>



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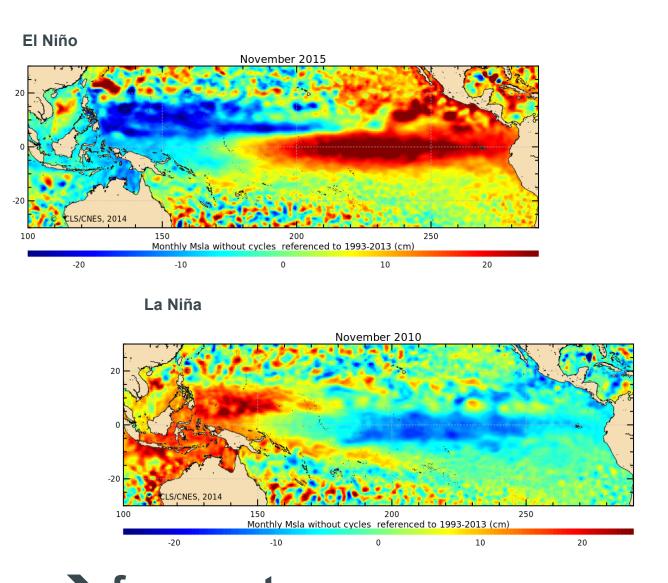
Gulf Stream eddies and associated currents

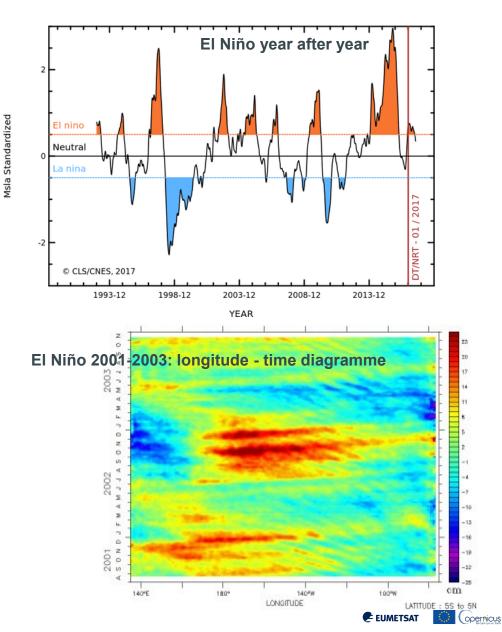


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What can sea heights show? Large-scale ocean-atmosphere coupled phenomena

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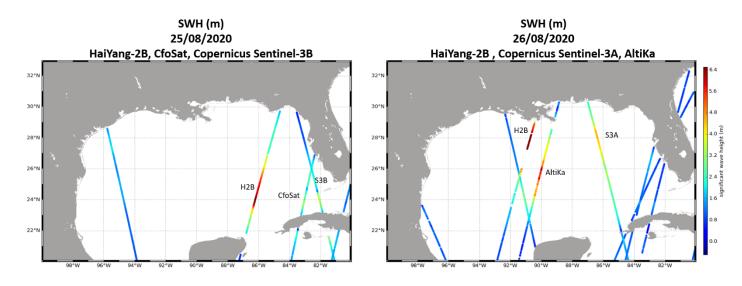
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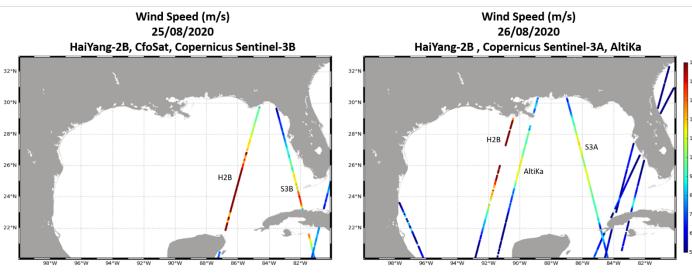
Ocean altimetry: not "only" sea surface height

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Significant wave height (SWH)

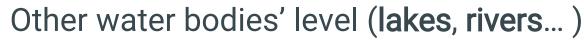
Wind speed (modulus)

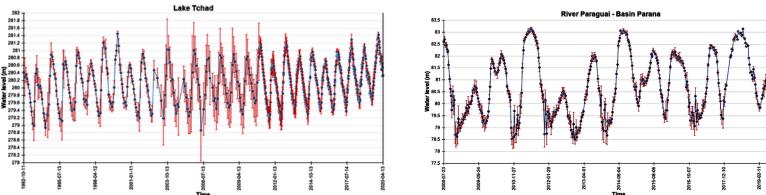




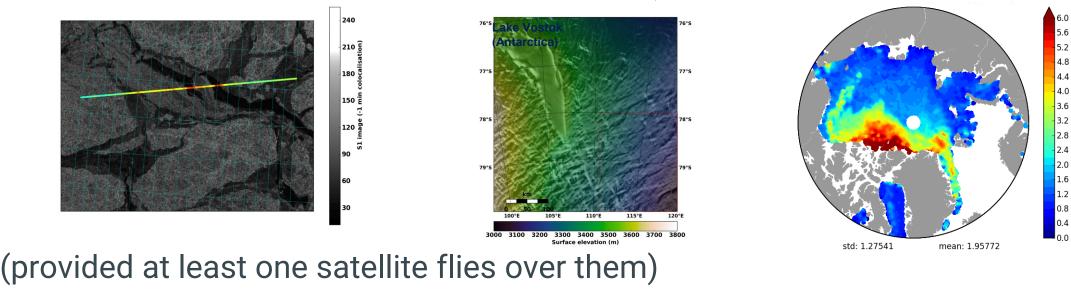
Altimetry: not only sea surface height & significant wave heights

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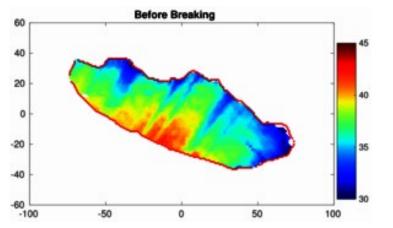
Ice topography, including leads and fractures (sea ice or ice sheets)

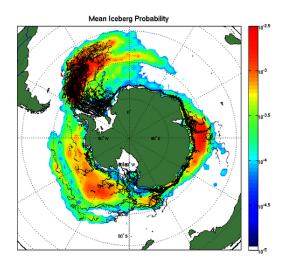


Altimetry: not only sea surface height & significant wave heights

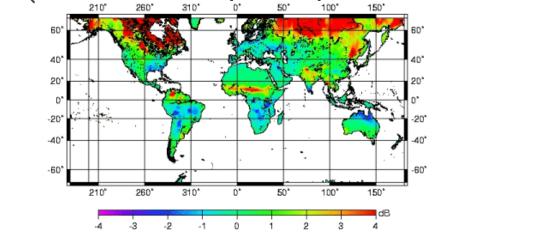
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Icebergs and some other reflectors on the ocean





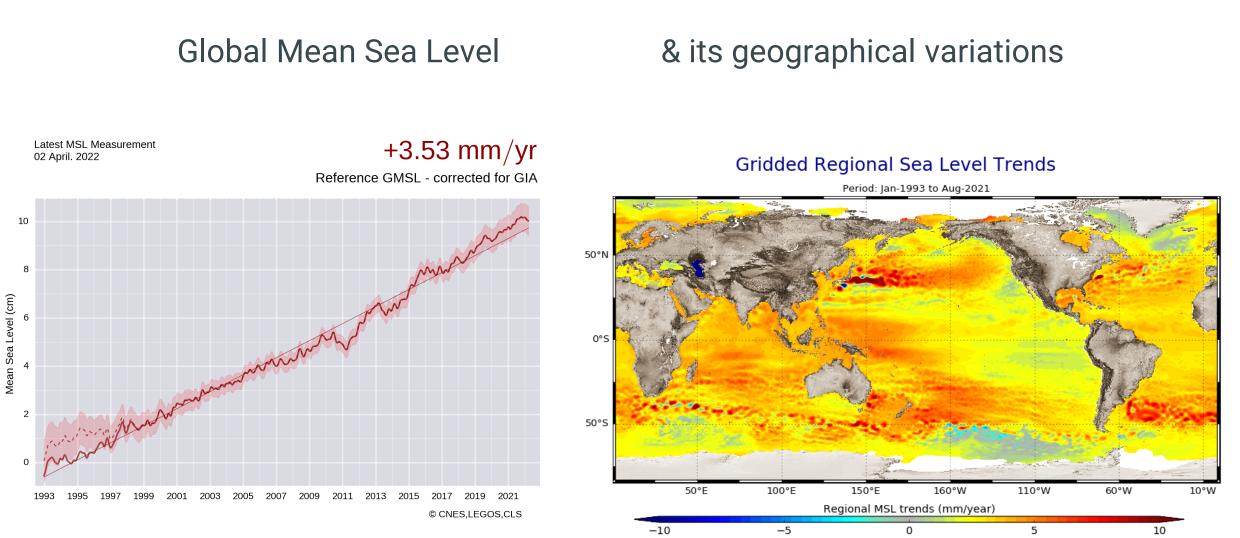
Some "solid land" (deserts, snow-covered areas) through the backscattered radar wave power (\rightarrow waveform power)



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What can sea heights show? Long-term global-averaged variations

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• Questions? \rightarrow go to Slido.com – event code: #EUMSC33

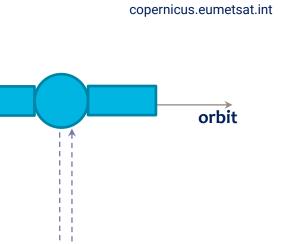
Surface Height & Significant wave height measurements

- Measure travel time 2T from emit to return of the radar pulse
- Speed of the radar pulse is light's celerity (c \approx 3x10⁸ m/s)
- The range h is deduced:

 $h = T \times c$

 The altitude of the satellite is also very precisely measured; water level is the difference:

Surface height = altitude - range



water surface

🗭 EUMETSAT

Reference ellipsoid

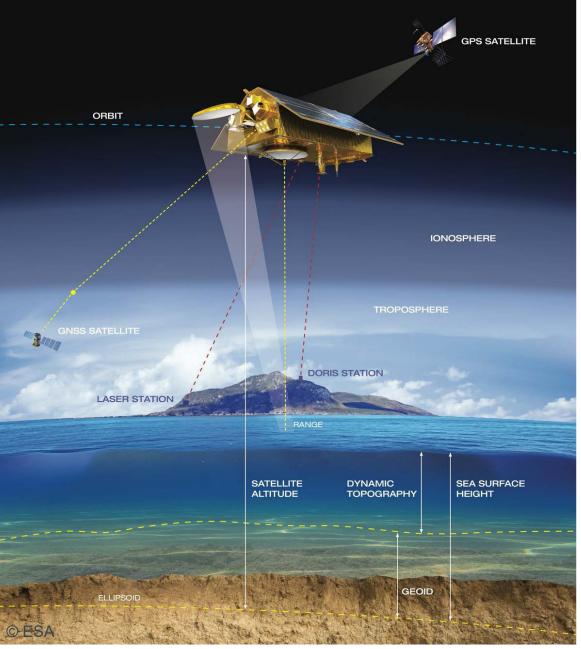
Surface height

(range)

altitude

geoid

How it works (slightly more realistic)



SSH_{corr} = Altitude – Range – Corrections

Range = satellite-to-surface distance

Altitude from the onboard instruments

Corrections applied:

- water in the troposphere ("wet tropo")
- electrons in the ionosphere
- dry gases in the atmosphere ("dry tropo")
- atmospheric pressure ("inverse barometer")
- sea state bias (wave crests reflect radar beam less than troughs)
- tides (ocean, solid Earth, pole)

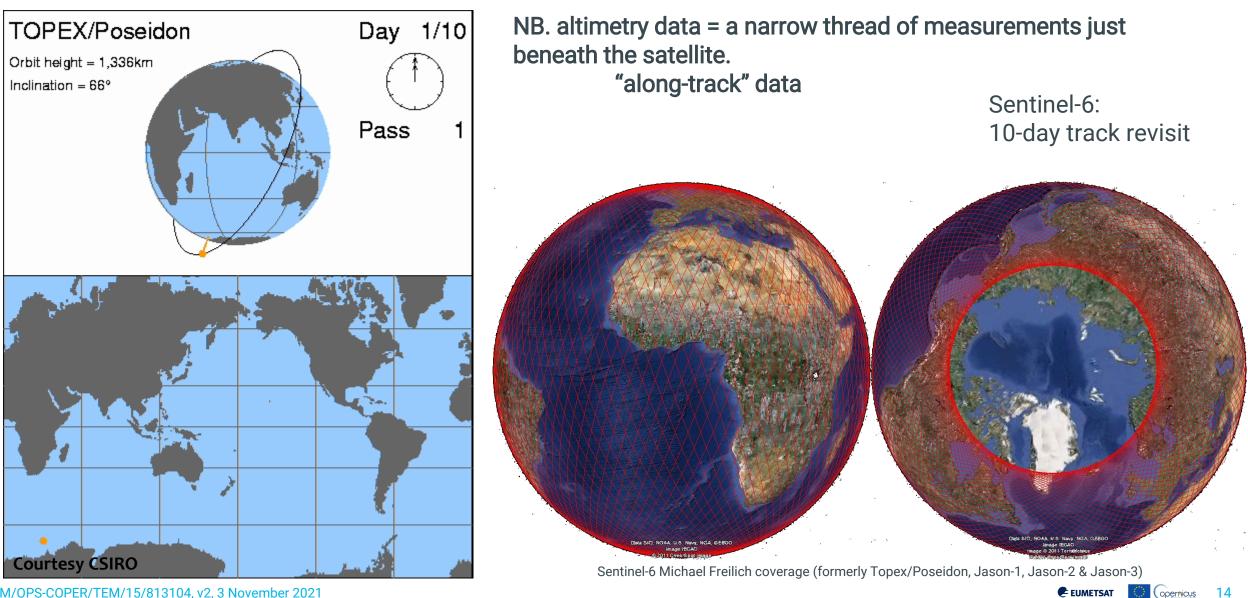
(All corrections are <u>subtracted</u> from the rough SSH)



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\square											
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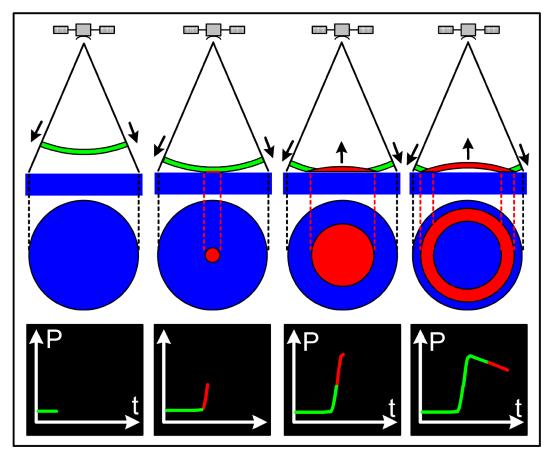
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In practice: analysis of radar (averaged) "echoes": waveforms

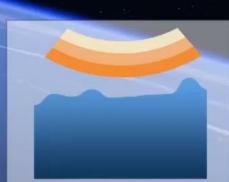
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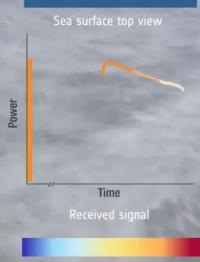
 The satellite-to-surface distance (aka "range") is retrieved from averaged echoes.

How an echo is "built"

Classical altimeter Calm sea Low resolution mode







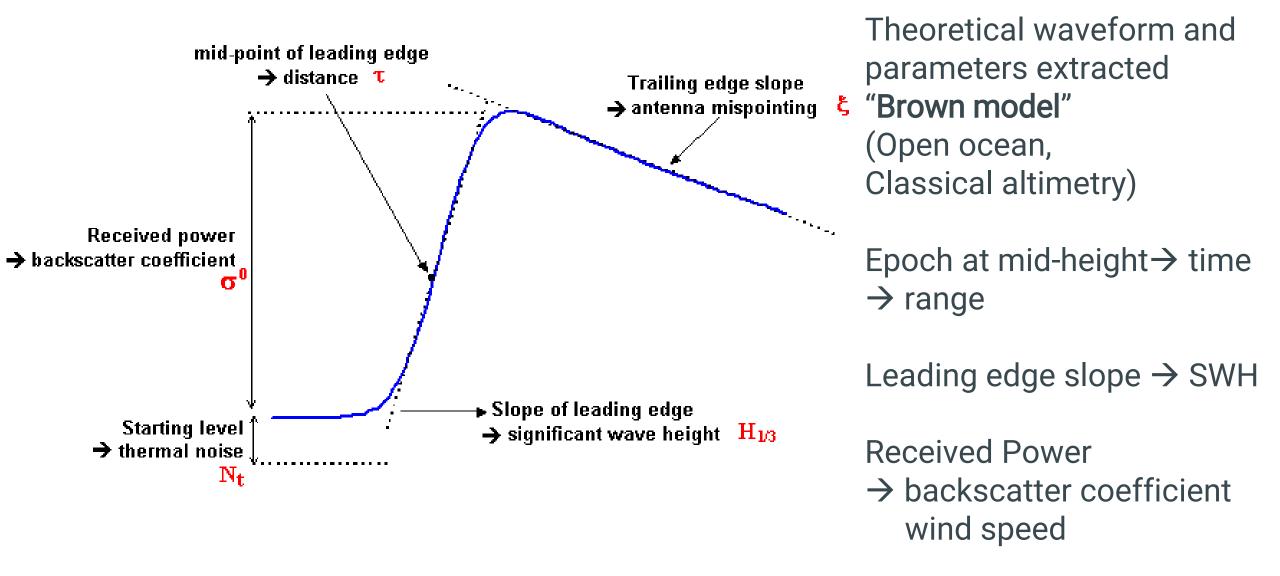
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N. Chan

Low Sea Surface Height High

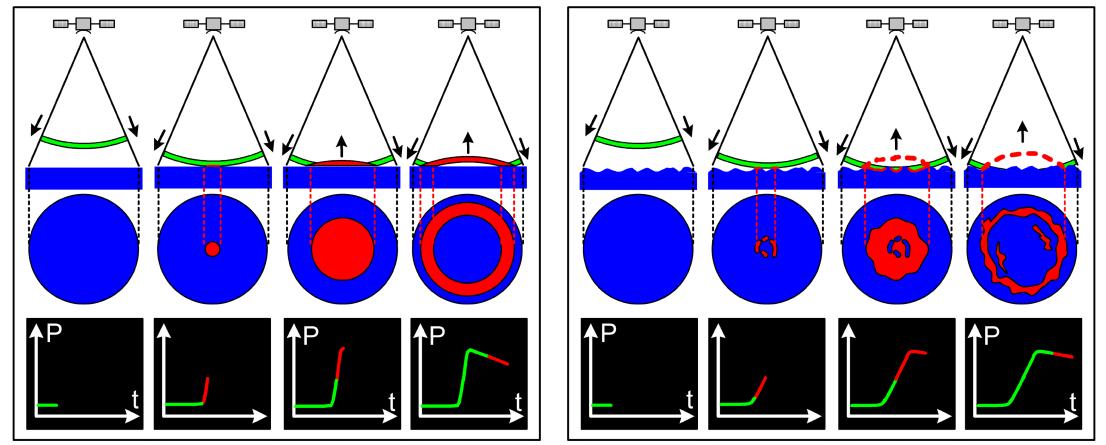
In real life: analysis of radar (averaged) "echoes": waveforms

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In practice: analysis of radar (averaged) "echoes": waveforms

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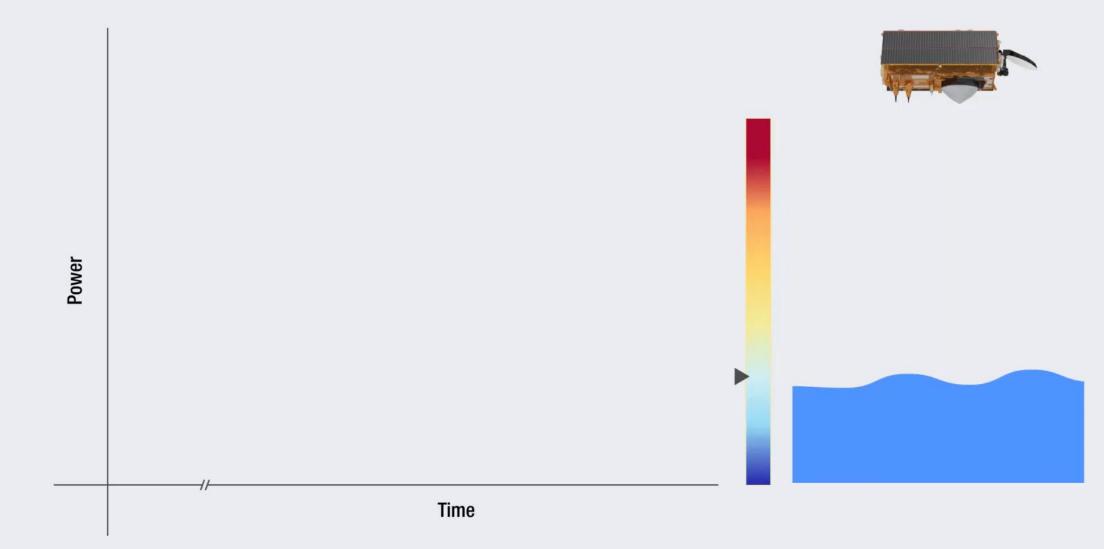


How an echo is "built"

Classical altimeter Calm sea How an echo is "built"

Classical altimeter Rough sea







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Sentinel-6 Michael Freilich inheritance & future

Altimetry early years

- Geos-3, Skylab as test bed (1973-75)
- Seasat the 1st "real" altimeter flying (1978)
- Geosat (US Navy) 1984-89
- Nasa, Cnes both had plans for a mission in the 1980s; they merged them into
 - **Topex** (US altimeter, with legacy from Geosat) / **Poseidon** (French altimeter), launched 10 Aug. 1992
- NB. In the meantime, ESA launched ERS-1 with an altimeter among other sensors (1991).
- Topex/Poseidon follow-on was Jason-1 (launched 2001), with only the Poseidon-2 altimeter onboard, then Jason-2 (2008), & 3 (2016) with Eumetsat and Noaa joining.

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Calibration & cross-calibration phase

- if possible, an altimetry satellite is launched to follow/precede closely its predecessor for at least 6 months
 - cross-calibration with the previous mission (Jason-3 for Sentinel-6 Michael Freilich).
 - calibration using *in situ*, statistics... of the mission (true for all EO satellites)



 There was more than 6 months of calibration phase for Sentinel-6 Michael Freilich, to also intercalibrate the redundant altimeter onboard (and because it was a brand new satellite).

• Sentinel-6 Michael Freilich declared fit for duty in March 2022

 Topex/Poseidon - Jason series: highest accuracy, cross-calibrated series \rightarrow "reference" mission for the Mean Sea Level variation measurements

MEASURING SEA-LEVEL CHANGE

Since the early 1990s, satellite altimeters have revolutionised our understanding of sea-level change





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Sentinel-6A (Jason-CS A) / Michael Freilich

- Altimetry-dedicated mission, non sun-synchronous (<u>not</u> in phase with tides)
- Launched on 21st Nov 2020
- To take over Jason-3 for at least 5.5 years
- continuous, intercalibrated, measurements on this orbit since Oct. 1992 (30 years soon!)
- Sentinel-6B (clone): launch planned in Nov. 2025



Onboard Sentinel-6A (Jason-CS A) / Michael Freilich

- Poseidon-4 Altimeter:
 - descending from Poseidon onboard Topex/Poseidon & the Poseidon altimeters onboard the Jasons
 - instrument & processing close to Sentinel-3's (except emission / reception pattern)
- Similar complement of
 - a radiometer and
 - 3 precise (independent) orbit determination instruments



Copernicus Programme in altimetry for the years to come...

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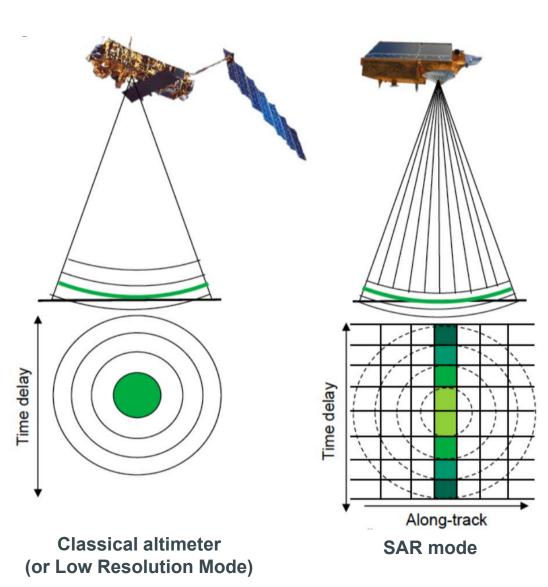
All above-listed missions controlled, processed and distributed by EUMETSAT

The follow-on of Sentinel-6B is currently under study

Sentinel-6 Michael Freilich improvements in altimetry

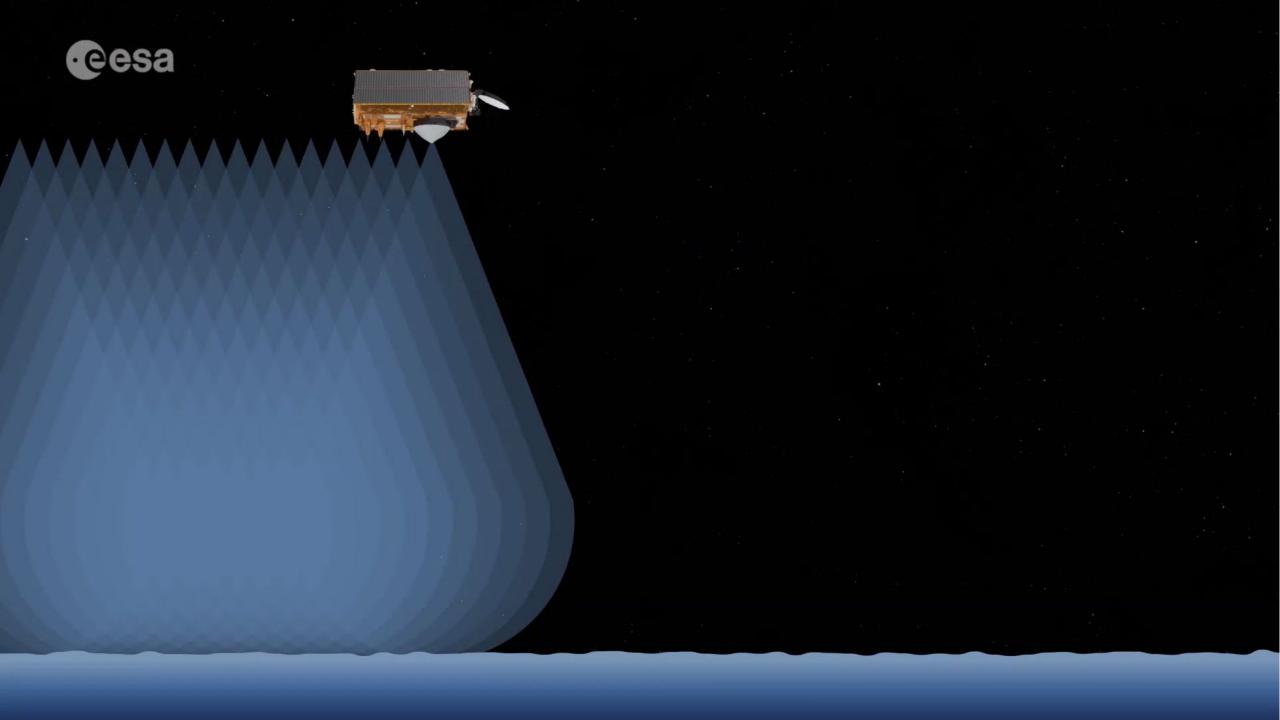
"SAR-Mode" on Sentinel-6 (also Cryosat2, Sentinel-3)

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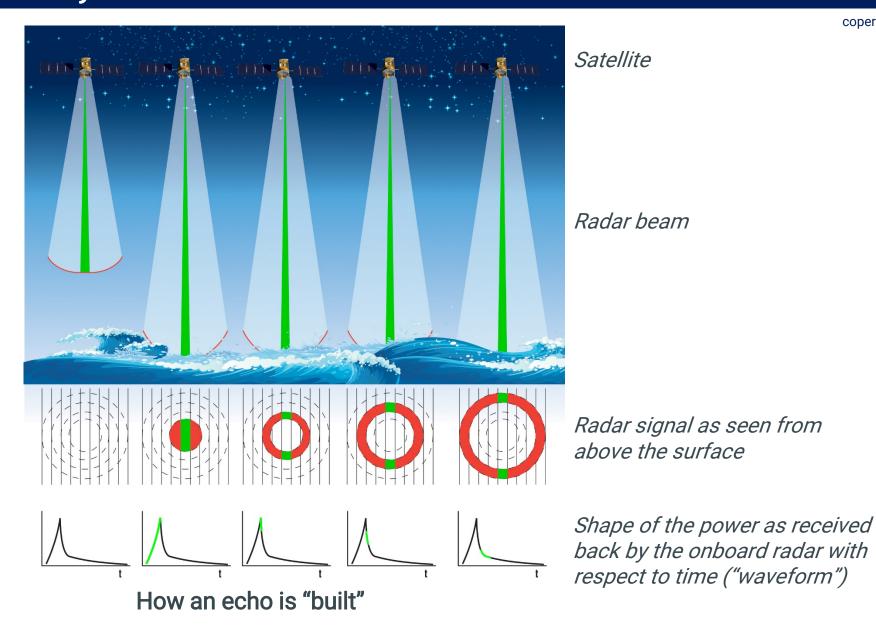


- Higher emission rate than previous (classical) altimeters
- Frequency received used to compute direction of the beam (Doppler shift)
- Coherence of the signal sent for about 2.5 s
- Split radar footprints in "slices", data over each slice averaged using different satellite positions
 better along-track resolution.

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In practice: analysis of radar "echoes": SAR waveforms



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High resolution synthetic aperture radar mode

Mesa

Simultaneous for and underesolution made

Delay-Doppler (or SAR-) altimetry advantages

Improvements wrt conventional altimetry:

 More observations of a same "slice" (also called stack data) to be averaged

→ lower noise → more accurate ranges with the finer along-track spatial resolution provided (~ 300 meters along-track, aka 20 Hz data)

- Less ambiguity about what surface is observed close to land
 - \rightarrow more-coastal altimetry

Sentinel-6 in High-Resolution (HR) over most Earth up to 66°N & S (ocean, ice, and land waters)

Performances (NRT/STC/NTC)

Range noise

- S6 (HR, 300 m) (observed, low SWH): 0.62 cm
- S6 (HR, 300 m) requirement:
 0.8 cm
- S6 (HR, 300 m) goal: 0.5 cm
- J3 (LR, 7 km): 1.8 cm

S6 (HR, 300 m) (observed)]				
66 (HR, 300 m) (requirement)									
S6 (HR, 300 m) (goal)]						
J3 (LR, 7 km) (observed)]]	
	0	1	2	3	4	5	6	7	

SSH RMS (cm)

□NTC □STC □NRT

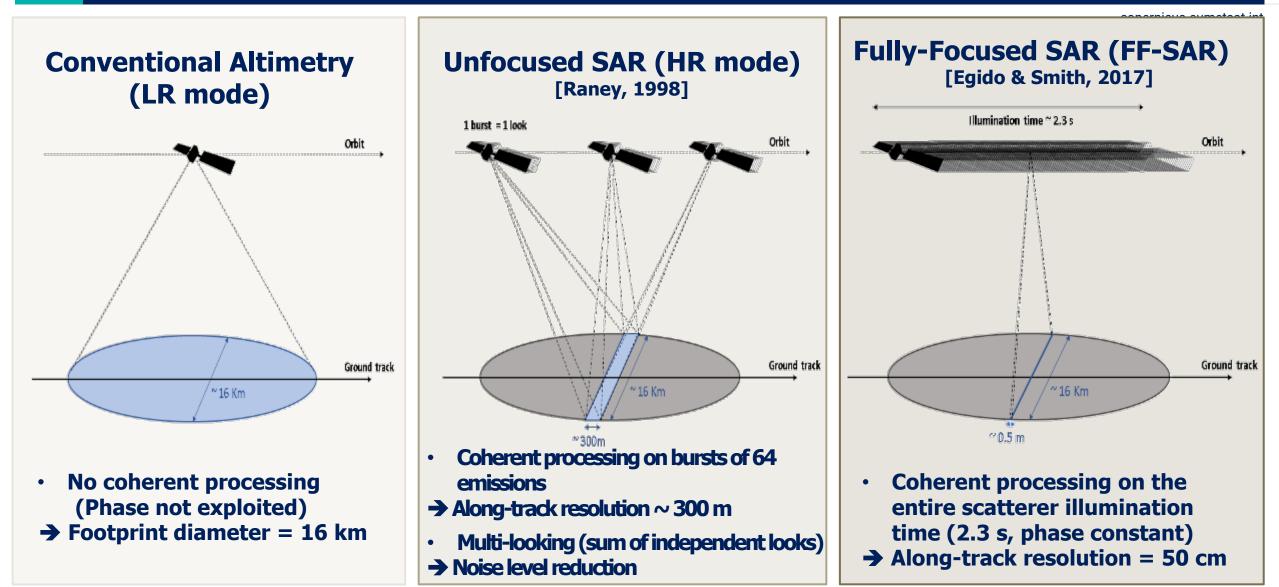
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Delay-Doppler (or SAR-) altimetry – current developments

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- A new capability: "fully-focused SAR" : processing the synthetic aperture using the longest possible integration time
 - ➔ 50 cm along-track resolution *possible* with specific processing of Level-1A data
- Outputs of this processing not currently in operational nor standard products
- Several studies ongoing, including swell-wave spectra, small water bodies, rivers, coastal ocean features, etc.

From Conventional to FF-SAR Altimeter processing



T/P, ERS, Jason, Envisat, Saral...

Cryosat-2 and Sentinel-3 Sentinel-6 standard processing

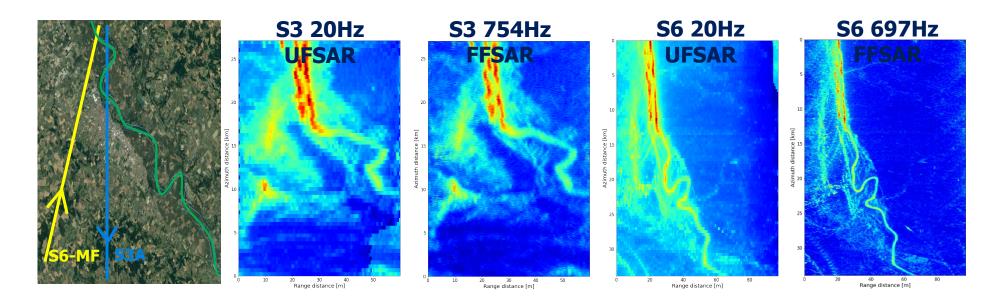


Sentinel-6; Sentinel-3 with a few ghost detections

specific processing

Benefits of FFSAR over rivers





Radargrams over Garonne river (France) at crossing point of S3A (cycle 10 pass 70) and S6-MF (cycle 68, pass 299).



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Sentinel-6 data products

• Level-1A

- Individual echoes; instrumental calibrations applied
- From this the user can create L1B-S with software (provided by ESA); FF-SAR processing
- Level-1B
 - Calibrated waveforms, to be combined with Level-2 to form the equivalent of Jason's Sensor Geophysical Data Records (SGDR)
- Level-2
 - Equivalent to Geophysical Data Records (GDR)
 - New NetCDF format with groups
 - Provided also in **reduced format** (with 1-Hz only) and in BUFR format (in NRT)
- Level-2P
 - As Level-2, with computed corrected heights, only essential variables & updated corrections and models, validation flag
- Level-3
 - Harmonised with other missions (also distributed by Copernicus Marine Service)

Data level and cooking

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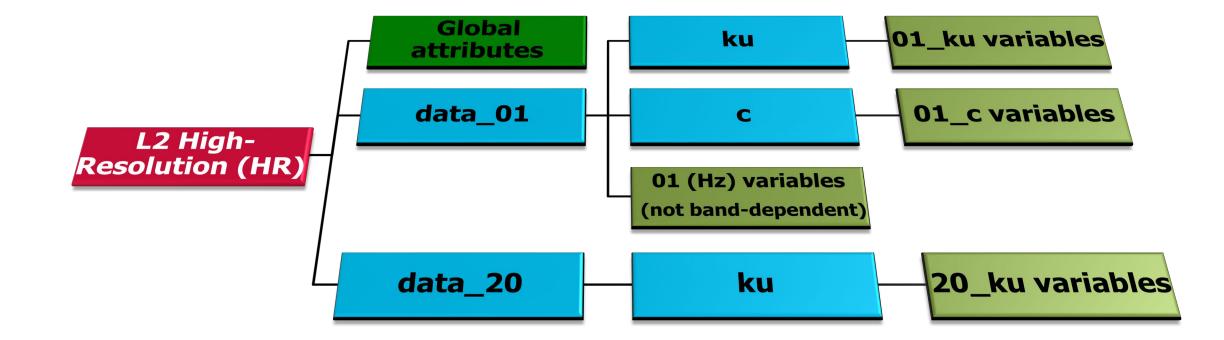
	Data	Tagliatelle al ragú
Level 0	(Space agencies)	Grow your wheat, your cow, pork tomatoes, carrots then cook, etc.
Level 1 S3 FBR S6 waveforms	Explore new processing, new parameters, other surfaces	Make your pasta from (bought) flour. Grow your vegetables, wash, peel and mince them.
Level 2 (aka GDRs)	Non-open ocean (non continental waters), change corrections,	Buy meat, tomatoes, vegetables and cook the ragú; buy pasta and cook them
Level 3 (multi-satellite)	Assimilation Change corrections precise SWH	Buy ragú sauce, pasta; add a pinch of thyme, some more meat and let it cook for a (long) time.
Level 4 (grids)	Open-ocean	Buy your tagliatelle al ragú from next door Italian take-away restaurant.
Visualization tools' outputs	(png images)	Photo of the plate (artistic or not)

Near-Real Time (NRT)	Short Time Critical (STC)	Non Time Critical (NTC)	
 Mainly for operational Met agencies (wind and wave mainly) Products split by satellite dump/granules (per ground 	 For ocean modelling and assimilation Product split by pass (pole to pole) NetCDF 	 For oceanographic and geophysical research and climate studies Products split by pass (pole to pole) NetCDF 	
station/10-minute chunks)NetCDF and BUFR		"Annual" reprocessing of	
	NTC products		
 3-hour latency OGDR 1-Hz and 20-Hz measurements (sea level, wind speed, wave height, etc.) 	 48-hour latency IGDR 1-Hz and 20-Hz measurements 	 With any major product evolution To ensure consistency of data standard throughout 	
	the mission		
 3-hour latency Level 2: Low- and high-resolution products Standard (1-Hz and 20-Hz) Reduced (1-Hz) BUFR (1-Hz and 20-Hz) Level 2P: Harmonised L2 (1-Hz) 	 36-hour latency Level 1A: Individual echoes (High-Resolution (HR) only) Level 1B: Low-Resolution (LR) and High-Resolution (HR) Level 2: Low-Resolution (LR) and High-Resolution (HR) Standard (1-Hz and 20-Hz) Reduced (1-Hz only) Level 2P: Harmonised L2 (1-Hz) Level 3: With orbit error correction, error information (1-Hz) 	 This is the new "climate product" Level 1B: Low-Resolution (LR) and High-Resolution (HR) Level 2: Low-Resolution (LR) and High-Resolution (HR) Standard (1-Hz and 20-Hz) Reduced (1-Hz only) Level 2P: Harmonised L2 (1-Hz) Level 3: With orbit error correction, error information (1-Hz) 	

- NetCDF data grouping
 - more convenient variable naming
 - Compartmentalise data (avoid a long list of fields only alphabetically-sorted)
- Separate High-Resolution (HR) and Low-Resolution (LR) products
- Waveforms in L1B product (link to L2 to have some corrections)
- "unique" internal filename, à la Jason ("SAFE" packaging)
- Separate Level 2 radiometer product (MWR)

Example: NetCDF groups in Level 2 High-Resolution (HR) product

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- Sentinel-6 introduces High-Resolution (HR) on the reference altimeter missions
 - "Interleaved mode" (radar emission/reception pattern) will allow Low-Resolution (LR)/High-Resolution (HR) simultaneously, thus ensuring continuity and opening the door to a lot more R&D
 - New type of data products
 - 1-Hz range noise below 1 cm at low SWH (0.62cm)!
- Sentinel-6 will produce Short-Time Critical data faster than
 previous Jason missions
 - Assimilation into ocean forecasting models
- All Sentinel-6 data produced by EUMETSAT
 - Availability through EUMETCast and EUMETSAT Data Archive
 - BUFR provided in NRT (through GTS, mainly for Met Offices)

Take-home message

Sentinel-6 Michael Freilich:

- Changes AND continuity
 - Benefitting from unremitting work on accuracy for the past 30 years
 - Enabling a seamless transition
 - Also improvements on data accuracy, capabilities
 - New possibilities to be explored...
 - Format close to the last Jason-3 format, reprocessing ongoing for older missions
- The story continues!

(Sentinel-6B to be launched Nov. 2025)



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