

The fully automated service of burned areas mapping in Italy based on Sentinel-2 and ancillary data

L. Pulvirenti¹, G. Squicciarino¹, E. Fiori¹, D. Negro², A. Gollini², S. Puca²

- ¹ CIMA Research Foundation
- ² Italian Department of Civil Protection





• The service

• The processor implementing the service

Validation of the maps of burned areas

Characteristics & Requirements

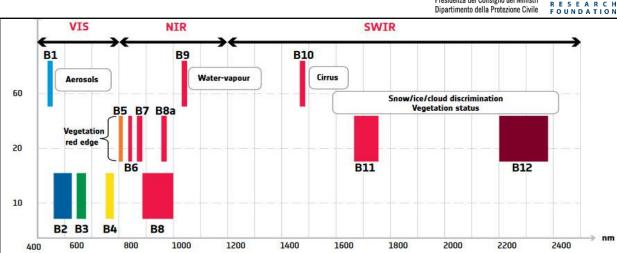


- Continuous nationwide (Italy) monitoring of burned areas (BAs) using multispectral data provided by the Sentinel-2 (S2) constellation
 - Systematic processing of all daily S2 images of the Italian territory (*cloud cover < 40%*)
- Includes *S2 data download, processing and publishing* of the daily BA maps on the *MyDEWETRA* web-gis platform (all automated)
- Operational 365 days/year
- Processing chain runs once a day at 00:00 to process images acquired the day before
- Spatial resolution of the BA maps: 20 m
- Minimum mapping unit: 1 ha

S2 coverage of Italy

- S2 is a multispectral imaging mission
 - 13 spectral bands —
- S2 constellation of 2 satellites allows for a revisit frequency of 5 days (under the same viewing conditions)
 - Overlap between swaths from adjacent orbits → revisit frequency may increase (different viewing conditions)
 - Cloud cover may imply longer revisit time

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Some numbers....

- Service working *since 2019* (pre-operational mode)
- Italy covered with 73 tiles subdivided along 6 orbits
 - S2 products available as tiles of fixed size (100 × 100 km²) along with a single orbit
- For each year, 1200-1500 S2 tiles (e.g., ~ 1300 in 2021) were processed (depending on the n° of tiles discarded due to clouds)
- During the 2019-2021 summer campaigns (fire season: June - September), more than 4000 tiles were processed









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The processor: AUTOBAM



- AUTOBAM (AUTOmatic Burned Areas Mapper) maps BA through a *change detection* approach
 - Applied to 3 spectral indices derived from S2 data
 - Carried out comparing the values of the indices at current time with the values derived from the most recent cloud-free S2 data
 - Implemented combining *different processing techniques* like clustering, edge filtering, adaptative buffering, automatic thresholding and region growing
- Among the available S2 data, *level 2A products* are used
 - Corrected for the effects of the atmosphere (surface reflectance ρ)
 - Include a scene classification map useful to *mask clouds and water bodies*
- S2 data complemented by *ancillary data*
 - MODIS-derived and VIIRS-derived hotspots (active fires)
 - fire notifications, from the firefighting fleet belonging to Joint Air Operating Centre (COAU)

AUTOBAM main steps (all automated)



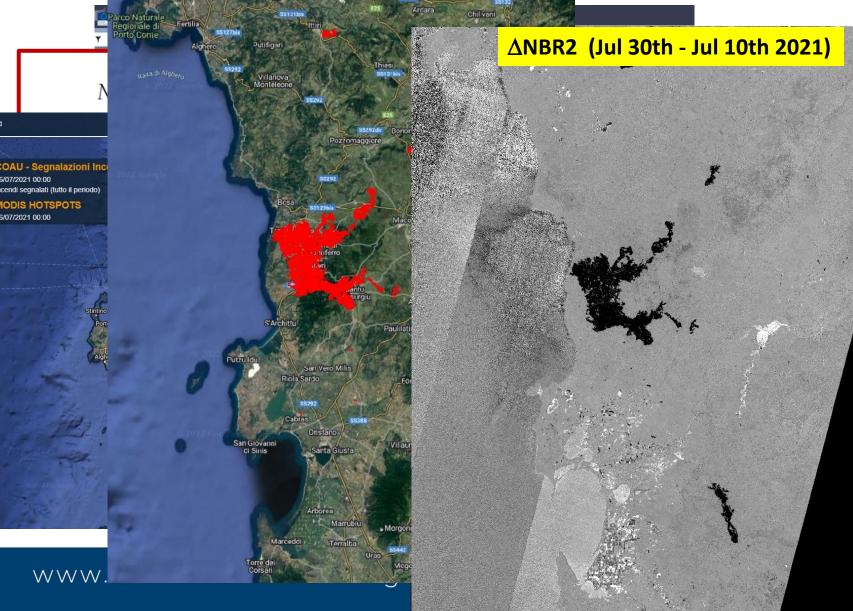
S2 data download

Computation of Spectral Indices (for for each tile)

Comparison with the values at previous time (most recent cloud free data)

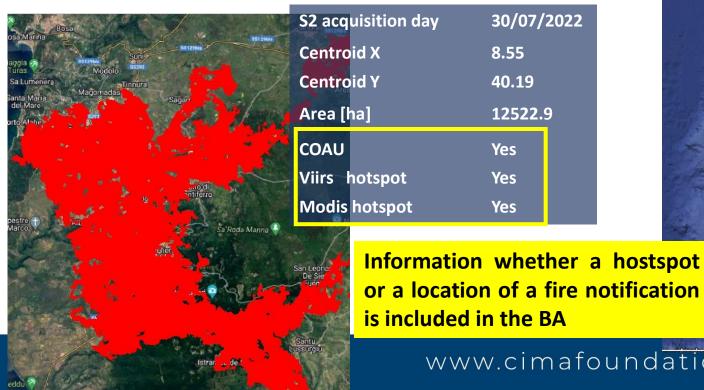
> Ingestion of Ancillary data

> Generation of the BA maps



AUTOBAM output

- Mosaic of the BA maps produced for the different tiles
 - Raster (Geotiff)
 - Shapefile
- Maps published on the MyDewetra platform











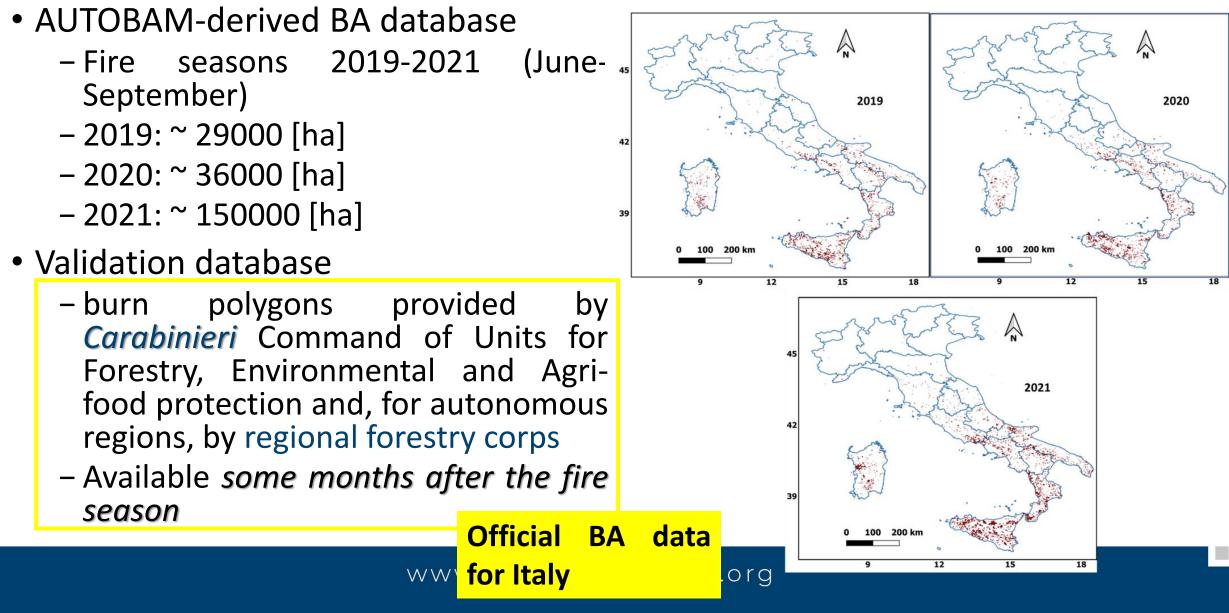
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Validation of the maps of burned areas

The BA database and the validation set





Validation exercises



- Validation set includes information about
 - -extent of each BA (in ha)
 - -fire date

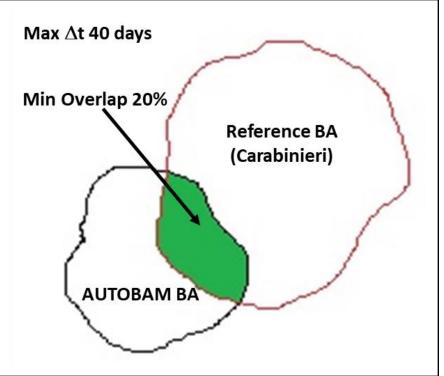
- Two validation exercises to evaluate:
 - -BA detection capability
 - -BA mapping accuracy

BA detection capability: procedure



- BA included in the validation set assumed as *reference*
- A reference BA is considered as detected by AUTOBAM if all the following conditions are fulfilled:
 - $A_{overlap} / A_{ref} > 20\%$
 - A_{overlap} /A_{AUTOBAM} >20%
 - $\Delta t \leq 40 \text{ days}$

 Δ t: difference between the S2 acquisition day and the fire date associated to each reference BA

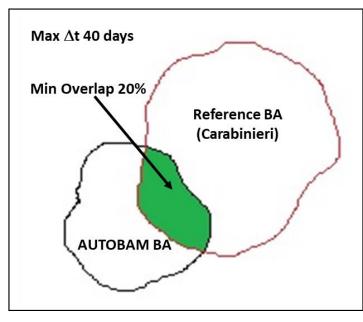


BA detection capability: results



year	N° Reference BAs	N° Detected BAs	N° Missed° BAs	Detected BAs %	Missed BAs %
2019	2117	1357	760	64.1	35.9
2020	1957	1201	756	61.4	38.6
2021	2923	1876	1047	64.2	35.8
2019-2021	6997	4434	2563	63.4	36.6

Detection count



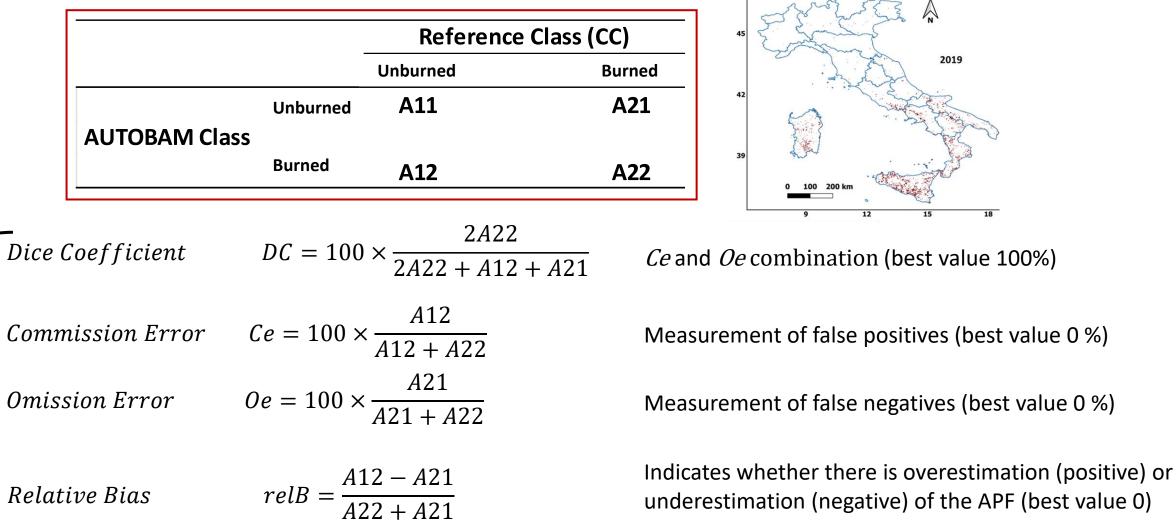
Total burned surface

year	Reference BAs [ha]	Detected BAs [ha]	Missed BAs [ha]	Overlapped BAs [ha]	Non-overlapped BAs [ha]	Overlapped BAs [%]	Non-overlapped Bas [%]
2019	34694.4	29069.6	6687.8	21637.5	13056.9	62.4	37.6
2020	42245.0	35786.5	8196.4	26736.7	15508.3	63.3	36.7
2021	147500.3	154754.1	18803.3	109284.6	38215.6	74.1	25.9
2019-2021	224439.7	219610.2	33687.5	157658.8	66780.9	70.2	29.8

BA mapping accuracy: evaluation

Accuracy metrics





BA mapping accuracy: results



year		AUTOBAM
	DC	48.1
2019	Се	61.2
2015	Ое	36.7
	RelB	63.1
	DC	58.4
2020	Се	47.8
2020	Ое	36.1
	RelB	22.4
	DC	76.4
2021	Се	27.9
2021	Oe	25.2
	RelB	3.8
	DC	68.6
2019 - 2021	Се	39.0
2017 - 2021	Ое	29.0
	RelB	16.4

To obtain the statistics of the BA by land cover type, the data from the CORINE Land Cover database were used

land cover		Forest	Shrubland
year			
	DC	74.7	82.8
2019 - 2021	Се	19.3	12.8
2019 - 2021	Oe	33.8	21.1
	relB	-18.0	-9.5

Main Critical Aspects



- Difficulties in detecting BAs in:
 - cropland
 - areas obscured by persistent cloud cover
 - areas hit by surface fires that do not impact the canopy
- AUTOBAM performances depend on the accuracy of the scene classification map included in the Sentinel-2 level 2A product, especially on the *reliability of the cloud detection*

Conclusions & Outlook



- AUTOBAM systematically processes all the S2 observations of Italy (cloud cover < 40%) to daily produce a BA map used by DPC and some regions in pre-operational mode
- Good BA detection capability
 - > 60% in terms of detection count
 - ~ 70% in terms of estimation of ha of BA
- Possibility to carry out similar validation exercises for other kind of satellite-derived BA data too (ref. data provided by Italian authorities)
- Possibility to ingest other ancillary data to improve BA mapping accuracy
 - From 2021 (Lazio) and 2022 (Abruzzo), a couple of regions are providing AUTOBAM with accurate fire notifications derived from their SOUP (Italian acronym of Permanent Unified Operations Room)





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Thank you for your attention

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info@cimafoundation.org www.cimafoundation.org