ECMWF ensemble products practicals and exercises

Baltic+ course – 8th November 2023

1) Based on what you have just learned look at the following Meteograms and circle the correct answers (from the text written in bold) or input the correct answers in the text.



- a. On Monday 20 March in the afternoon there is **LOW / HIGH** uncertainty in the total precipitation total.
- b. The High Resolution forecast (blue line) generally **AGREES / DISAGREES** with the ensemble forecast
- c. At midday (12 UTC) on Friday 24th March:
- d. The forecast is for NO RAIN / A LITTLE RAIN / LOTS OF RAIN
- e. The ensemble members generally **AGREE / DISAGREE** this suggests **LOW UNCERTAINTY / HIGH UNCERTAINTY**
- f. At 00 UTC on Tuesday 28th March, one ensemble member is forecasting a high of _____mm of rain, this is AN EXTREME / THE MEAN VALUE / VERY LOW
- g. Write two sentences summarising what this meteogram is forecasting for precipitation over the next 10 days



2) Using OpenCharts (<u>www.charts.ecmwf.int</u>) and the Extra-tropical Cyclone Database (CDB) (<u>https://sites.ecmwf.int/charts/cdb/</u>) create a forecast using ensemble products only for **Riga, Latvia on Saturday 11**th **November**. Below are ensemble products I'd like you to find and look at and include in your forecast:

- Extra-Tropical Cyclone Database
- Ensemble mean and spread
- Meteograms
- Extreme Forecast Index (EFI)
- Precipitation Type

Things to consider / include:

- Uncertainty in the forecast / the spread of the ensemble
- Model jumpiness
- How you would communicate any uncertainty



3) Answer the questions below which relate to ensemble forecasting

a. What is the main advantage of an ensemble forecast?

- i. To provide forecasts months in advance
- ii. To give minute-by-minute forecasts
- iii. To give a quantitative assessment of risk

b. What are the three main sources of error in NWP forecasts?

- i. Initial condition uncertainty, model uncertainties and human errors
- ii. Initial condition uncertainty, model uncertainties and boundary condition uncertainty
- iii. Model uncertainties, time uncertainties and boundary condition uncertainty

c. What does a nearly vertical Cumulative Distribution Function (CDF) suggest?

- i. Bi-model distribution of values
- ii. Good agreement between ensemble members
- iii. Ensemble members don't agree

d. Why do we use Shift of Tails (SOT)?

- i. To indicate which type of weather will be extreme
- ii. Because it has a nice name
- iii. Because it provides information on how extreme an event might be

e. What is the control ensemble member?

- i. The member run from unperturbed initial conditions
- ii. The highest resolution member
- iii. The member started from the largest perturbation of initial conditions

f. What are meteograms?

- i. A product that shows information about the tracks and intensities of storms in the forecast
- ii. A way to represent the ensemble forecast for a single location
- iii. A product focusing on the extremes of the distribution

g. How many perturbed ensemble members does ECMWF run?

- i. 50 in both the 15-day ENS and extended range
- ii. 50 in the 15-day ENS and 100 in the extended range
- iii. 100 in both the 15-day ENS and extended range

